Lectures on the integrability of the 6-vertex model.

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Contents

1	Intr	oduction	4
2	Clas	ssical integrable spin chains	5
	2.1	Classical r -matrices and the construction of classical integrable	
		spin chains	5
	2.2	Classical L-operators related to $\widehat{sl_2}$	6
	2.3	Real forms	8
		2.3.1	8
		2.3.2	8
	2.4	Integrable classical local SU_2 -spin chains	9
3	Qua	antization of local integrable spin chains	10
	3.1	Quantum integrable spin chains	10
	3.2	The Yang-Baxter equation and the quantization	10
	3.3	Quantum Lax operators and representation theory	11
		3.3.1 Quantum LSL_2	11
	3.4	Irreducible representations	14
		3.4.1	14
		3.4.2	15
		3.4.3	15
		3.4.4	15
		3.4.5	16
		3.4.6 Real forms	16
	3.5	The fusion of R -matrices and the degeneration of tensor products	
		of irreducibles	16
	3.6	Higher transfer-matrices	18
	3.7	Local integrable quantum spin Hamiltonians	19
		3.7.1 Homogeneous $SU(2)$ spin chains	19

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		3.7.2 Inhomogeneous $SU(2)$ spin chains	20
4	The 4.1 4.2 4.3	$\begin{array}{c} \textbf{spectrum of transfer-matrices} \\ \textbf{Diagonalizability of transfer-matrices} \\ \textbf{Bethe ansatz for } sl_2 \\ \textbf{The completeness of Bethe vectors} \\ 4.3.1 \\ 4.3.2 \\ 4.3.3 \\ \end{array}$	21 21 23 23 24 25
5	The	thermodynamical limit	25
6	The 6.1 6.2 6.3 6.4 6.5	6-vertex model The 6-vertex configurations and boundary conditions	26 26 27 28 31 32 32 33 34 34 35 35
7	The 7.1 7.2 7.3	6-vertex model on a torus in the thermodynamic limit The thermodynamic limit of the 6-vertex model for the periodic boundary conditions	36 36 37 37 38
8	The 8.1 8.2 8.3	6-vertex model at the free fermionic point Homogeneous case	38 38 39 40 42 42 43

9	The	free energy of the 6-vertex model	45
	9.1	The phase diagram for $\Delta>1$	45
		9.1.1	45
		9.1.2	45
		9.1.3	45
	9.2	The phase diagram $ \Delta < 1$	49
	9.3	The phase diagram $\Delta < -1$	50
		9.3.1 The phase diagram	50
		9.3.2 The antiferromagnetic region	51
10	Som	e asymptotics of the free energy	53
10		The scaling near the boundary of the <i>D</i> -region	53
		The scaling in the tentacle	54
		The 5-vertex limit	55
		The asymptotic of the free energy near the tricritical point in the	00
		5-vertex model	56
	10.5	The limit $\Delta \to -1^-$	57
		The convexity of the free energy	57
11		Legendre Transform of the Free Energy	58
			58
	11.2		59
12	The	limit shape phenomenon	60
		The Height Function for the 6-vertex model	60
		Stabilizing Fixed Boundary Conditions	62
	12.3	The Variational Principle	63
		12.3.1	63
		12.3.2 The variational principle	64
		12.3.3	64
	12.4	Limit shapes for inhomogeneous models	65
	12.5	Higher spin 6-vertex model \dots	65
13	Sem	iclassical limits	66
10		The semiclassical limits in Bethe states	66
		The semiclassical limits in the higher spin 6-vertex model	66
		The large N limit in spin-1/2 spin chain as a semiclassical limit .	67
	10.0	13.3.1	67
		13.3.2	68
		13.3.3	69
			50
14	The	free fermionic point and dimer models	69

\mathbf{A}	Syn	aplectic and Poisson manifolds	74
	A.1		74
	A.2		
	A.3		75
В	Clas	ssical integrable systems and their quantization	7 5
	B.1	Integrable systems in Hamiltonian mechanics	75
\mathbf{C}	Pois	sson Lie groups	76
	C.1	Poisson Lie groups	76
	C.2	Factorizable Poisson Lie groups and classical r -matrices	77
	C.3		77
	C.4	Symplectic leaves	78
D	Qua	antization	7 9
	D.1	Quantization	79
		D.1.1 Quantized algebra of observables	79
	D.2	Examples of family deformations	80
		D.2.1	80
		D.2.2	80
	D.3	Quantization of integrable systems	81

1 Introduction

The goal of these notes is to outline the relation between solvable models in statistical mechanics, and classical and quantum integrable spin chains. The main examples are the 6-vertex model in statistical mechanics, and spin chains related to the loop algebra Lsl_2 .

The 6-vertex model emerged as a version of the Pauling's ice model, more generally, as a two-dimensional model of ferroelectricity. The free energy per site was computed exactly in the thermodynamical limit by E. Lieb [23]. The free energy as a function of electric fields was computed by Sutherland and Yang [37]. For details and more references on earlier works on the 6-vertex model see [24]. The structure of the free energy as a function of electric fields was also studied in [27][6].

Baxter descovered that Boltzman weights of the 6-vertex model can be arranged into a matrix which staisfies what is now known as the Yang-Baxter equation. For more references on the 6-vertex model and on the consequences of the Yang-Baxter equation for the weights of the 6-vertex model see [3].

The 6-vertex model and similar 'integrable' models in statistical mechanics became the subject of renewed research activity after the discovery of Sklyanin of the relation between the Yang-Baxter relation in the 6-vertex model and the quantization of classical integrable systems [34]. It lead to the discovery of many 'hidden' algebraic structures of the 6-vertex model and to the construction of quantizations of a number of important classical field theories [13][14]. For more

references see, for example [19]. Further development of this subject resulted in the development of quantum groups [11] and further understanding of algebraic nature of integrability.

Classical spin chains related to the Lie group SL_2 is an important family of classical integrable systems related to the 6-vertex model. The continuum version of this model is known as Landau-Lifshitz model. One of its quantum counterparts, the Heisenberg spin chain has a long history. Eigenvectors of its Hamiltonian of the Heisenberg model were constructed by Bethe in 1931 using the substitution which is known now as the Bethe ansatz. He expressed the eigenvalues of the Hamiltonian in terms of solutions to a system of algebraic equations known now as Bethe equations. An algebraic version of this substitution was found in [14].

These lectures consist of three major parts. First part is a survey of some basic facts about classical integrable spin chains. The second part is a survey of the corresponding quantum spin chains. The third part is focus on the 6-vertex model and on the limit shape phenomenon. The Appendix has a number of random useful facts.

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2 Classical integrable spin chains

The notion of a Poisson Lie group developed from the study of integrable systems and their relation to solvable models in statistical mechanics.

It is a geometrical structure behind Poisson structures on Lax operators, which emerged in the analysis of Hamiltonian structures in integrable partial differential equations. First examples of these structures are related to taking semiclassical limit of Baxter's *R*-matrix for the 8-vertex model. The notion of Poisson Lie groups and Lie bialgebras places these examples into the context of Lie theory and provides a natural versions of such systems related to other simple Lie algebras.

2.1 Classical r-matrices and the construction of classical integrable spin chains

Here we will recall the construction of classical integrable systems based on classical r-matrices.

A classical r-matrix with (an additive) spectral parameter is a holomorphic function on \mathbb{C} with values in $End(V)^{\otimes 2}$ which satisfies the classical Yang-Baxter

equation:

$$[r_{12}(u), r_{13}(u+v)] + [r_{12}(u), r_{23}(v)] + [r_{13}(u+v), r_{23}(v)] = 0$$
 (1)

where $r_{ij}(u)$ act in $V^{\otimes 3}$, such that $r_{12}(u) = r(u) \otimes 1$, $r_{23}(u) = 1 \otimes r(u)$, etc.

Let L(u) be a holomorphic function on \mathbb{C} of certain type (for example a polynomial). Matrix elements of coefficients of this function satisfy quadratic r-matrix Poisson brackets if Their generating function L(u) has the Poisson brackets

$$\{L_1(u), L_2(v)\} = [r(u), L_1(u)L_2(v)]$$
(2)

where $L_1(u) = L(u) \otimes 1$, $L_2(u) = 1 \otimes L(u)$. The expression on the left is the collection of Poisson brackets $\{L_{ij}(u), L_{kl}(v)\}$.

Consider the product

$$T(u) = L^{(N)}(u - a_N) \dots L_1^{(1)}(u - a_1)$$

Matrix elements of T(u) are functions on $P_N \times \cdots \times P_1$. The factor $L^{(i)}$ is the function on P_i . The Poisson structure on P_i is as above.

The r-matrix Poisson brackets for $L^{(i)}(u)$ imply similar Poisson brackets for $T_{ij}(u)$:

$$\{T_1(u), T_2(v)\} = [r(u-v), T_1(u)T_2(v)]$$

Taking the trace in this formula we se that

$$\{t(u), t(v)\} = 0$$

Fix symplectic leaves $S_i \subset P_i$ for each *i*. The restriction of the generating function t(u) to the product of symplectic leaves $S = S_N \times \cdots \times S_1 \subset P_N \times \cdots \times P_1$ gives the generating function for commuting functions on this symplectic manifold.

Under the right circumstances the generating function t(u) will produce the necessary number of independent functions to produce a completely integrable system, i.e. dim(S)/2.

One of the main conceptual questions in this construction is: Why classical r-matrices exist? Indeed, if n = dim(V), the equation (1) is a system of n^6 functional equations for n^4 functions. The construction of the Drinfeld double of a Lie bialgebra provides an answer to this question [11].

2.2 Classical L-operators related to \widehat{sl}_2

In this section we will focus on classical L-operators for the classical r-matrix corresponding to the standard Lie bialgebra structure on \widehat{sl}_2 .

Such L-operators describe finite dimensional Poisson submanifolds in the infinite dimensional Poisson Lie group LSL_2 . For some basic facts and references see Appendix A. Up to a scalar multiple they are polynomials in the

spectral variable z. One of such simplest Poisson submanifolds correspond to polynomials of first degree of the following form:

$$L(u) = \begin{pmatrix} a + a'z^2 & b' \\ z^2b & c + c'z^2 \end{pmatrix}$$
 (3)

where $z = \exp(u)$. The r-matrix Poisson brackets on L(u) with the r-matrix given by (98) induce a Poisson algebra structure on the algebra of polynomials in a, b, \ldots This Poisson algebra can be specialized further (by quotienting with respect to corresponding Poisson ideal). As a result we arrive to the following L-operator:

$$L(u) = \begin{pmatrix} zk - z^{-1}k^{-1} & z^{-1}f \\ zf & zk^{-1} - z^{-1}k \end{pmatrix}$$
 (4)

which satisfies the r-matrix Poisson brackets (2) with the following brackets on k, e, f:

$$\{k, e\} = \epsilon k e, \quad \{k, f\} = -\epsilon k f$$
 (5)

$$\{e, f\} = 2\epsilon (k^2 - k^{-2}),\tag{6}$$

The function

$$c = ef + k^2 + k^{-2}, (7)$$

Poisson commute with all other elements of this Poisson algebra, i.e. it is the Casimir function. It is easy to show that this is the only Casimir function on this Poisson manifold.

It is easy to check that

$$L(-u)^t = -D_z \sigma_2^y L(u) \sigma_2^y D_z^{-1}$$
(8)

On the level surface of c parameterized as $c=t^2+t^{-2}$ this matrix satisfies the extra identity

$$L(u)\theta(L(-u))^t = (zt-z^{-1}t^{-1})(tz^{-1}-t^{-1}z)I$$

where I is the identity matrix and

$$\theta(e) = f$$
, $\theta(f) = e$, $\theta(k) = k$

is the anti-Poisson involution: $\{\theta(a)\theta(b)\}=-\theta(\{a,b\}), \ \theta^2=id$

Its easy to find the determinant of L(u):

$$\det(L(u)) = (zt - z^{-1}t^{-1})(t^{-1}z - tz^{-1})$$

When $z = t, t^{-1}$ the matrix L degenerates to one dimensional projectors.

$$L(t) = \begin{pmatrix} \frac{tk - t^{-1}k^{-1}}{t^{-1}e} \\ 1 \end{pmatrix} \otimes (t^{-1}e, tk^{-1} - t^{-1}k)$$
 (9)

$$L(t^{-1}) = \begin{pmatrix} \frac{t^{-1}k - tk^{-1}}{te} \\ 1 \end{pmatrix} \otimes (te, t^{-1}k^{-1} - tk)$$
 (10)

2.3 Real forms

2.3.1

Here we will describe the Poisson manifold su_2^* . Let S_1, S_2, S_3 be the coordinates su_2^* corresponding to the usual orthonormal basis in su_2 . The Poisson brackets between these coordinate functions are

$$\{S_1, S_2\} = 2S_3, \{S_2, S_3\} = 2S_1, \{S_3, S_1\} = 2S_2,$$

These coordinates are also known as classical spin coordinates. The center of

this Poisson algebra is generated by $C=S_1^2+S_2^2+S_3^2$. It is convenient to introduce $S^+=(S_1+iS^2)/2$, $S^-=(S_1-iS^2)/2$. Since S_i are real, $\overline{S^+} = S^-$.

The Poisson brackets between these coordinates are:

$$\{S^+, S^-\} = -iS_3, \ \{S_3, S^{\pm}\} = \mp 2iS^{\pm}$$

Level surfaces of C are spheres. On the level surface with $C = l^2$ with two point $S_3 = \pm l$ being removed we have the following Darboux coordinates:

$$S^{+} = e^{i\phi}\sqrt{pl - p^2}, \quad S^{-} = e^{-i\phi}\sqrt{pl - p^2}, \quad S_3 = l - 2p$$

where $0 and <math>0 < \phi \le 2\pi$ and $\{p, \phi\} = 1$.

2.3.2

The Poisson algebra

$$\{k, e\} = \epsilon k e, \quad \{k, f\} = -2\epsilon k f,$$

 $\{e, f\} = 2\epsilon (k^2 - k^{-2})$

has the two real forms which are important for spin chains with compact phase spaces:

- The real form with $\epsilon = 1$, |k| = 1, $e = \overline{f}$.
- And the real form where $\epsilon = i$, $e = \overline{f}$, and $\overline{k} = k$.

In the first case the level surface of (7) with $c = 2\cos 2R$ without two points e = f = 0 has the following Darboux coordinates:

$$e = 2e^{i\phi}\sqrt{\sin(p)\sin(2R-p)}, \quad f = 2e^{-i\phi}\sqrt{\sin(p)\sin(2R-p)}, \quad k = e^{i(R-p)}$$

with $\{p, \phi\} = 1$, and $0 and <math>0 < \phi \le 2\pi$.

Similarly, in the second case the level surface $c = 2 \cosh R$ without two points e = f = 0 have Darboux coordinates

$$e=2e^{i\phi}\sqrt{\sinh(p)\sinh(2R-p)}, \quad f=2e^{-i\phi}\sqrt{\sinh(p)\sinh(2R-p)}, \quad k=e^{R-p}$$

where $\phi \in \mathbb{R}$, $0 , and <math>\{p, \phi\} = 1$.

We will denote these level surfaces by $S^{(R)}$. In the compact case $S^{(R)}$ is diffeomorphic to a sphere. It can be realized as the unit sphere with the symplectic form dependent on R.

2.4 Integrable classical local SU_2 -spin chains

Because the $S^{(R)}$ is a symplectic leaf of the Poisson Lie group LGL_2 , the Cartesian product

 $\mathcal{M}^{R_1,\dots,R_N} = S^{(R_1)} \times \dots \times S^{(R_N)}$

is a Poisson submanifold in LGL_2 , which means matrix elements of the monodromy matrix

$$T(z) = L^{(R_1)}(za_1)L^{(R_2)}(za_2)\dots L^{(R_N)}(za_N)$$
(11)

satisfy the r-matrix Poisson brackets.

In order to obtain local Hamiltonians in the homogeneous classical spin chain $a_1 = \cdots = a_N = 1$, $R_1 = \cdots = R_N = R$ one can use the degenerations (9), (10). Combining these formulae (9), (10), and (8) we obtain the following identities:

$$L(t) = \alpha \otimes \beta^t$$
, $L(t^{-1}) = -\sigma^y D\beta \otimes \alpha^t D^{-1} \sigma^y$

where column vector α and row vector β^t are given in (9). These identities imply

$$tr(T(t)) = \prod_{n=1}^{N} (\beta_n, \alpha_{n+1}), \quad tr(T(t^{-1})) = (-1)^N \prod_{n=1}^{N} (\alpha_n, \beta_{n+1})$$

Here we assume the periodicity $\alpha_{N+1} = \alpha_1$ and $\beta_{N+1} = \beta_1$. Now notice that

$$tr(L_n(t)L_{n+1}(t)) = (\alpha_n, \beta_{n+1})(\beta_n, \alpha_{n+1})$$

One the other hand this trace can be computed explicitly:

$$tr(L_n(t)L_{n+1}(t)) = e_n f_{n+1} + f_n e_{n+1} + (tk_n - t^{-1}k_n^{-1})(tk_{n+1} - t^{-1}k_{n+1}^{-1}) + (tk_n^{-1} - t^{-1}k_n)(tk_{n+1}^{-1} - t^{-1}k_{n+1})$$
(12)

This gives the first local Hamiltonian

$$H = \log(tr(T(t))tr(T(t^{-1}))) = \sum_{n=1}^{N} \log(e_n f_{n+1} + f_n e_{n+1} + (tk_n - t^{-1}k_n^{-1})(tk_{n+1} - t^{-1}k_{n+1}^{-1}) + (tk_n^{-1} - t^{-1}k_n)(tk_{n+1}^{-1} - t^{-1}k_{n+1}))$$
(13)

Other local spin Hamiltonians can be chosen as logarithmic derivatives of tr(T(z)) at when $z=t^{\pm 1}$, for details see [14] and references therein.

When N is even and inhomogeneities are alternating $a_1 = a, a_2 = a^{-1}, a_3 = a, \ldots, a_N = a^{-1}$ there is a similar construction of local Hamiltinians also based on degenerations (9), (10). Again, all logarithmic derivatives of T(z) at points $z = at^{\pm 1}, a^{-1}t^{\pm 1}$ are local spin Hamiltonians.

In the continuum limit the Hamiltian dynamics generated by these Hamiltians converges to the Landau-Lifshitz equation, see [14] and references therein.

3 Quantization of local integrable spin chains

3.1 Quantum integrable spin chains

In the appendix ?? there is a short discussion of integrable quantization of classical integrable system.

A quantization of a local classical integrable spin chin is an integrable quantization of a classical local integrable spin chain such that quantized Hamiltonians remain local. That is the collection of the following data:

- A choice of the quantization of the algebra of observables of the classical system (in a sense of the section Appendix ??), i.e a family of associative algebras with a *-involution which deform the classical Poisson algebra of observables.
- A choice of a maximal commutative subalgebra in the algebra which is a quantization of Poisson commuting algebra of classical integrals.
- In addition, locality of the quantization means that the quantized algebra of observables is the tensor product of local algebras (one for each site of our one-dimensional lattice): $A_h = \bigotimes_{n=1}^N B_h^{(n)}$, and that the quantum Hamiltonian has the same local structure as the classical Hamiltonian (??):

$$H = \sum_{n} H_n$$

where
$$H_n = 1 \otimes \cdots \otimes H^{(k)} \otimes \cdots \otimes 1$$
 and $H^{(k)} \in B_h^{(n)} \otimes B_h^{(n+1)} \otimes \cdots \otimes B_h^{(n+k)}$.

• A *-representation of the algebra of observables (the space of pure states of the system).

3.2 The Yang-Baxter equation and the quantization

Here we will describe the approach to the quantization of classical spin chains with r-matrix Poisson bracket for polynomial Lax matrices based on construction of corresponding quantum R-matrices and quantum Lax matrices.

In modern language the construction of quantum R-matrix means the construction of the corresponding quantum group, and the construction of the quantum L-matrix means the construction of the corresponding representation of the quantum group.

Suppose we have a classical integrable system with commuting integrals obtained as coefficients of the generating function $\tau(u)$ described in section 2.1. The R-matrix quantization means the following:

• Find a family R(u,h) of invertible linear operators acting in $V \otimes V$ such that for each h they satisfy the quantum Yang-Baxter equation

$$R_{12}(u,h)R_{13}(u+v,h)R_{23}(v,h) = R_{23}(v,h)R_{13}(u+v,h)R_{12}(u,h)$$

and when $h \to 0$

$$R(u,h) = 1 + hr(u) + O(h^2)$$

where r(u) is the classical r-matrix.

• Let the classical Lax matrix L(u) be a matrix valued function of u of certain type (for example a polynomial of fixed degree), with matrix elements generating a Poisson algebra with Poisson brackets (2). For given R(u, h) define the quantization of this Poisson algebra as the associative algebra generated by matrix elements of the matrix $\mathcal{L}(u)$ of the same type as L(u) (for example a polynomial of the same degree) with defining relations

$$R(u,h)\mathcal{L}(u+v)\otimes\mathcal{L}(v) = (1\otimes\mathcal{L}(v))(\mathcal{L}(u+v)\otimes 1)R(u,h), \tag{14}$$

Denote such algebra by B_h .

• Consider the generating function

$$T(u) = \mathcal{L}_1(u - w_1) \otimes \dots \mathcal{L}_N(u - w_N)$$
(15)

acting in $End(V) \otimes B_h^{(1)} \otimes \cdots \otimes B_h^{(N)}$. It is easy to see that the commutation relations (14) imply

$$R(u,h)T(u+v)\otimes T(v) = (1\otimes T(v))(T(u+v)\otimes 1)R(u,h), \tag{16}$$

The invertibility of R(u,h) together with the relations (16) imply that $t(u) = tr_V(T(u)) \in B_h^{(N)} \otimes \cdots \otimes B_h^{(1)}$ is a generating function for a commutative subalgebra in $B_h^{(N)} \otimes \cdots \otimes B_h^{(N)}$:

$$[t(u), t(v)] = 0$$

Under the right circumstances this commutative subalgebra is maximal and defines an integrable quantization of the corresponding classical integrable spin chain.

The R-matrix was found by Baxter. Sklyanin discovered that when $h \to 0$ the classical R-matrix defines a Possion structure on LGL_2 defined by the formula (100) and that it implies the Poisson commutativity of traces.

There is an algebraic way to derive the Baxter's R-matrix from the universal R-matrix for $U_q(\widehat{gl_2})$. It is outlined in the appendix.

3.3 Quantum Lax operators and representation theory

3.3.1 Quantum LSL_2

Here is the formal definition of $C_q(\widehat{SL}_2)$ in terms of generators and relations. Let q be a nonzero complex number. The algebra $C_q(\widehat{SL}_2)$ is a complex algebra generated by elements the $T_{ij}^{(k)}$, where i, j = 1, 2 and $k \in \mathbb{Z}$. Consider the matrix $\mathfrak{T}(z)$ which is the generating function for the elements $T_{ij}^{(k)}$

$$\Im(z) = \sum_{k=1}^{\infty} T^{(k)} z^{2k} + \begin{pmatrix} T_{11}^{(0)} & T_{12}^{(0)} \\ 0 & T_{22}^{(0)} \end{pmatrix}.$$
 (17)

The determining relations in $C_q(\widehat{SL}_2)$ can be written as the following matrix identity with entries in $C_q(\widehat{SL}_2)$:

$$R(z)\mathfrak{I}(zw)\otimes\mathfrak{I}(w) = (1\otimes\mathfrak{I}(w))(\mathfrak{I}(zw)\otimes 1)R(z),$$

$$\mathfrak{I}(qz)_{11}\mathfrak{I}(z)_{22} - \mathfrak{I}(qz)_{12}\mathfrak{I}(z)_{21} = 1,$$

$$(18)$$

where the tensor product is the tensor product of matrices. Matrix elements in this formula are multiplied as elements of $C_q(\widehat{GL}_2)$ in the order in which they appear.

The matrix R(z) acts in $\mathbb{C}^2 \otimes \mathbb{C}^2$ and has the following structure in the tensor product basis:

$$R(z) = \begin{pmatrix} 1 & 0 & 0 & 0\\ 0 & f(z) & z^{-1}g(z) & 0\\ 0 & zg(z) & f(z) & 0\\ 0 & 0 & 0 & 1 \end{pmatrix}.$$
 (19)

where

$$f(z) = \frac{z - z^{-1}}{zq - z^{-1}q^{-1}}, \quad g(z) = \frac{(q - q^{-1})}{zq - z^{-1}q^{-1}}$$

It satisfies the Yang-Baxter equation.

Remark 1. There is important function s(z):

$$s(z) = q^{-1/2} \frac{(z^2 q^2; q^4)_{\infty}^2}{(z^2; q^4)_{\infty} (z^2 q^4; q^4)_{\infty}},$$

where

$$(x;p)_{\infty} = \prod_{k=1}^{\infty} (1 - xp^n).$$

the matrix

$$\Re(z) = s(z)R(z)$$

satisfies what is known in physics unitarity and the crossing symmetry:

$$\Re(z)\Re(z^{-1})^t = 1$$
, $\Re(z^{-1})^{t_2} = C_2\Re(zq^{-1})C_2$

where t is the transposition with respect to the standard scalar product in $\mathbb{C}^{2\otimes}$, t_2 is the transposition with respect to second factor in the tensor product, and $C_2 = 1 \otimes C$ where

$$C = \left(\begin{array}{cc} 0 & -i \\ i & 0 \end{array}\right)$$

The Hopf algebra structure on $C_q(\widehat{SL}_2)$ is determined by the following action of the antipode on the generators:

$$\Delta(\mathfrak{I}_{ij}(z)) = \sum_{k=1,2} \mathfrak{I}_{ik}(z) \otimes \mathfrak{I}_{kj}(z).$$
 (20)

The right side here, as well as in the second relation in (18), is understood as a product of Laurent power series. The antipode is determined by the relation

$$\Im(z)(S\otimes id\Im(z))=1.$$

Let d be a nonzero complex number. The identity (18) implies that the power series

$$\tau_1(z;d) = d\mathfrak{I}_{11}(z) + d^{-1}\mathfrak{I}_{22}(z) \tag{21}$$

generates a commutative subalgebra in $C_q(\widehat{SL}_2)$.

Chose a linear basis (for example ordered monomials in $T_{ij}^{(k)}$). The relations between generators will give the multiplication rule for monomials which will depend on q. This multiplication turns into the commutative multiplication of coordinate functions when q=1. The commutator of two monomials, divided by q-1, at q=1 becomes the Poisson bracket. It is easy to check that this Poisson brackets is exactly the one defined by the classical r-matrix (98).

Remark 2. Let D be a diagonal matrix. It is easy to see that $[D \otimes 1 + 1 \otimes D, R(x)] = 0$. It is easy to show that if

$$R(z)\mathfrak{I}_1(zw)\mathfrak{I}_2(w) = \mathfrak{I}_2(w)\mathfrak{I}_1(zw)R(z)$$

then

$$\tilde{R}(z) = (z^D \otimes 1)R(z)(z^{-D} \otimes 1), \quad \tilde{\mathfrak{I}}(z) = z^D \mathfrak{I}(z)z^{-D}$$

satisfy the same relation

$$\tilde{R}(z)\tilde{\mathfrak{I}}_1(zw)\tilde{\mathfrak{I}}_2(w) = \tilde{\mathfrak{I}}_2(w)\tilde{\mathfrak{I}}_1(zw)\tilde{R}(z)$$

In particular $\tilde{R}(z)$ satisfies the Yang-Baxter equation. Choosing D=diag(-1/2,1/2) gives the R-matrix (19) but with no factors $z^{\pm 1}$ off-diagonal. This symmetric version of the R-matrix is the matrix of Boltzmann weights in the 6-vertex model.

Remark 3. If A is an invertible diagonal matrix such that $(A \otimes A)R(z) = R(z)(A \otimes A)$ and $\Im(z)$ is as above then

$$\mathfrak{T}^A(z) = A\mathfrak{T}(z)A^{-1}$$

also satisfies the relations (18).

3.4 Irreducible representations

3.4.1

It is easy to check that the following matrix satisfies the R-matrix commutation relations (18)

$$\mathcal{L}(z) = \begin{pmatrix} zkq^{\frac{1}{2}} - z^{-1}k^{-1}q^{-\frac{1}{2}} & z^{-1}q^{-\frac{1}{2}}f \\ zq^{\frac{1}{2}}e & zk^{-1}q^{\frac{1}{2}} - z^{-1}kq^{-\frac{1}{2}} \end{pmatrix}$$
(22)

if e, f, k commute as

$$ke = qek, kf = q^{-1}fk,$$

 $ef - fe = (q - q^{-1})(k^2 - k^{-2}).$

Denote this algebra C_q .

The element

$$c = fe + k^2q + k^{-2}q^{-1} (23)$$

generates the center of this algebra.

It is clear that this algebra quantizes the Poisson algebra (5)(6). Indeed, the algebra C_1 is the commutative algebra generated by $e, f, k^{\pm 1}$. Consider the monomial basis $e^n k^m f^l$ in C_q . Fix the isomorphism between C_q and C_1 identifying these bases. The associative multiplication in C_q is given in this basis the function of q:

$$e_i e_j = \sum_k m_{ij}^k(q) e_k$$

it is clear that when q=1 this multiplication is the usual multiplication in the commutative algebra generated by e, f, k, k^{-1} . The skew symmetric part of the derivative of m(q) at q=1 is the Poisson structure.

The algebra C_q is a Hopf algebra with the comultiplication acting on generators as

$$\Delta k = k \otimes k, \ \Delta e = e \otimes k + k^{-1} \otimes e, \Delta f = f \otimes k + k^{-1} \otimes f$$

The algebra C_q is closely related to the quantized universal enveloping algebra for sl_2 . Indeed, elements $E = ek/(q-q^{-1}), F = k^{-1}f/(q-q^{-1}), K = k^2$ are generators for $U_q(sl_2)$:

$$KE = q^2 EK, \quad KF = q^{-2} FK, \quad EF - FE = \frac{K - K^{-1}}{q - q^{-1}}$$

with

$$\Delta K = K \otimes K, \ \Delta E = E \otimes K + 1 \otimes E, \Delta F = F \otimes 1 + K^{-1} \otimes F$$

3.4.2

Assume that q is generic. Denote by $V^{(m)}$ the irreducible m+1-dimensional representation of C_q , and by $v_0^{(m)}$ the highest weight vector in this representation:

$$kv_0^{(m)} = q^{\frac{m}{2}}v_0^{(m)}, \ ev_0^{(m)} = 0$$

The weight basis in this representation can be obtained by acting f on the highest weight vector. Properly normalized the action of C_q on the weight basis is:

$$kv_n^{(m)} = q^{\frac{m}{2} - n}v_n^{(m)}, \quad fv_n^{(m)} = (q^{m-n} - q^{-m+n})v_{n+1}^{(m)}, \quad ev_n^{(m)} = (q^n - q^{-n})v_{n-1}^{(m)}.$$

The Casimir element c acts on V(m) by the multiplication on $q^{m+1}+q^{-m-1}$. Because the algebra C_q is a Hopf algebra, it acts naturally on the tensor product of representations.

3.4.3

Denote the matrix (22) evaluated in the irreducible representation $V^{(m)}$ by $\mathcal{L}^{(m)}(z)$. It is easy to check that it satisfies the following identities:

$$\mathcal{L}^{(m)}(z^{-1})^t = -D_z C \mathcal{L}^{(m)}(zq) C^{-1} D_z^{-1}$$

$$\mathcal{L}^{(m)}(z)^T \mathcal{L}^{(m)}(z^{-1}) = (zq^{\frac{m+1}{2}} - z^{-1}q^{-\frac{m+1}{2}})(z^{-1}q^{\frac{m+1}{2}} - zq^{-\frac{m+1}{2}})I$$

where D_z is a diagonal matrix.

Here t is the transposition with respect to the standard scalar product in \mathbb{C}^2 and T is the transposition t combined with the transposition in $V^{(m)}$ with respect to the scalar product $(v_n^{(m)}, v_{n'}^{(m)}) = \delta_{n,n'}$.

3.4.4

The matrix (22) defines a family of 2-dimensional representations of $C_q(\widehat{SL_2})$. If a is a non-zero complex number such representation is

$$\mathfrak{I}(z) \mapsto g_m(z) \mathcal{L}^{(m)}(za)$$

where the factor $g_m(z)$ is important only if we want to satisfy the second relations which play the role of quantum counter-parts of the unimodularity (i.e. det = 1) of $\Im(z)$.

$$g_m(z) = -z \frac{(t^{-1}q^3z^2; q^4)_{\infty} (tq^5z^2; q^4)_{\infty}}{(t^{-1}qz^2; q^4)_{\infty} (tq^3z^2; q^4)_{\infty}}$$

3.4.5

The comultiplication defines the tensor product of irreducible representations described above

$$\Im(z) \mapsto \prod_{i=1}^{N} g_{m_i}(z/a_i) T^{(m_1, \dots, m_N)}(z|a_1, \dots, a_N)$$
(24)

where

$$T^{(m_1,\ldots,m_N)}(z|a_1,\ldots,a_N) = \mathcal{L}_1(z/a_1)\ldots\mathcal{L}_N(z/a_N),$$
 (25)

where we have taken the matrix product of the matrices $\mathcal{L}(z)$ as 2×2 matrices. The *n*-th factor in (25) acts on the *n*-th factor of $V^{(m_1)} \otimes \cdots \otimes V^{(m_N)}$.

Notice that this is also a tensor product of representations of C_q .

3.4.6 Real forms

As in the classical case there are two real form of the algebra C_q which are important for finite dimensional spin chains.

Recall that a *-involution of a complex associative algebra is an ani-involution of the algebra, i.e. $(ab)^* = b^*a^*$ which is complex anti-linear: $(\lambda a)^* = \bar{\lambda}a^*$. A real form of a complex A corresponding to this involutions is real algebra which is the real subspace in A spanned by the *-invariant elements.

When |q| = 1, we will write $q = \exp(i\gamma)$, the relevant real form of C_q , is characterized by the *-involution which acts on generators as

$$e^* = f$$
, $k^* = k^{-1}$

When q is real positive we will write $q = \exp(\eta)$. In this case the relevant real form is characterized by the * involution acting on generators as:

$$e^* = f$$
, $f^* = e$, $k^* = k$

As $\gamma \to 0$ or $\eta \to 0$ these real forms become real forms of the corresponding Poisson algebras described in section 2.3 with $\epsilon = i$ and $\epsilon = 1$ respectively.

3.5 The fusion of R-matrices and the degeneration of tensor products of irreducibles

This section is the analog of the construction of quantum L-operators by taking the tensor product of 2-dimensional representations.

Consider the product of R-matrices acting in the tensor product of n+m copies of \mathbb{C}^2 :

$$R_{1'2'\dots m',12\dots n}(z) = R_{1'1}(z) \qquad R_{1'2}(zq) \qquad \dots \qquad R_{1'n}(zq^{n-1})$$

$$R_{2'1}(zq) \qquad R_{2'2}(zq^2) \qquad \dots \qquad R_{2'n}(zq^n)$$

$$\dots \qquad \dots \qquad \dots \qquad \dots$$

$$R_{m'1}(zq^{m-1}) \qquad R_{m'2}(zq^m) \qquad \dots \qquad R_{m'n}(zq^{n+m-2})$$

The operator R(z) satisfies the identities

$$R(z)R^{t}(z^{-1}) = (zq - z^{-1}q^{-1})(z^{-1}q - zq^{-1})$$

 $PR(z)P = R^{t}(z)$

where t is the transpiration operation (with respect to the tensor product of the standard basis in \mathbb{C}^2), and

$$det(R(z)) = (zq - z^{-1}q^{-1})^3(z^{-1}q - zq^{-1})$$

From here we conclude that the matrix PR(z) degenerates at z=q and $z=q^{-1}$ to the matrices of rank 3 and 1 respectively.

Define

$$P_{12...n}^{+} = \check{\mathbf{R}}_{12}(q) \quad \check{\mathbf{R}}_{23}(q^{2}) \quad \dots \quad \check{\mathbf{R}}_{1n}(q^{n-1}) \\
\check{\mathbf{R}}_{23}(q) \quad \dots \quad \check{\mathbf{R}}_{2n}(q^{n-2}) \\
\dots \\
\check{\mathbf{R}}_{n-1n}(q) \tag{26}$$

where $\check{\mathbf{R}}(z) = PR(z)$ and P is the permutation matrix, $P(x \otimes y) = y \otimes x$.

Consider $(\mathbb{C}^2)^{\otimes n}$ as a representation of C_q . Because all finite dimensional representations of this algebra are completely reducible, it decomposes into the direct sum of irreducible components. The irreducible representation $V^{(n)}$ appears in this decomposition with multiplicity 1. One can show that the operator (26) is the orthogonal projector to $V^{(n)}$. The proof can be found in [22].

Also, it is not difficult to show that

$$P_{12...n}^{+}R_{1',12...n}(zq^{-\frac{n-1}{2}})P_{12...n}^{+} = (zq^{-\frac{n-3}{2}} - z^{-1}q^{\frac{n-3}{2}})\dots(zq^{\frac{n-1}{2}} - z^{-1}q^{-\frac{n-1}{2}})R_{1',[12...n]}^{(1,n)}(z)$$
(27)

where the linear operator $R^{1,n}(z)$ acts in $\mathbb{C}^2 \otimes V^{(n)}$ and the second factor appears as the q-symmetrized part of the tensor product $\mathbb{C}^{2^{\otimes N}}$. Moreover, it is easy to show that this operators is conjugate by a diagonal matrix to $\mathcal{L}(z)$:

$$R^{(1,n)}(z) \simeq \begin{pmatrix} zkq^{\frac{1}{2}} - z^{-1}k^{-1}q^{-\frac{1}{2}} & z^{-1}q^{-\frac{1}{2}}f\\ zq^{\frac{1}{2}}e & zk^{-1}q^{\frac{1}{2}} - z^{-1}kq^{-\frac{1}{2}} \end{pmatrix}$$

where e, f, k act in the n+1 dimensional irreducible representation as it is described in section 3.4. In this realization of the irreducible representation weight vectors appear as $v_k^{(n)} = P_{1...n}^+ e_1 \otimes e_1 \otimes e_2 \otimes e_2$ where we have n-k copies of e_1 and k copies of e_2 in this tensor product.

Similarly

$$P_{1'2'\dots m'}^{+}P_{12\dots n}^{+} \quad R_{1'1}(zq^{-\frac{n+m-2}{2}}) \quad \dots \quad R_{1'n}(zq^{\frac{n-m}{2}})$$

$$R_{2'1}(zq^{-\frac{n+m-4}{2}}) \quad \dots \quad R_{2'n}(zq^{\frac{n-m+2}{2}})$$

$$\dots \quad \dots$$

$$P_{1'2'\dots m'}^{+} \quad P_{12\dots n}^{+} =$$

$$(zq^{-\frac{n+m-4}{2}} - z^{-1}q^{\frac{n+m-4}{2}}) \quad \dots \quad (zq^{-\frac{n-m}{2}} - z^{-1}q^{-\frac{n-m}{2}}) \\ \dots \quad \dots \quad \dots \quad \dots \\ (zq^{-\frac{n-m-2}{2}} - z^{-1}q^{-\frac{n-m-2}{2}}) \quad \dots \quad (zq^{\frac{n+m-2}{2}} - z^{-1}q^{-\frac{n+m-2}{2}}) \\ R^{(m,n)}(z)$$

Here we assume that m < n. The matrix elements of $R^{(m,n)}(z)$ are Laurent polynomials of the form $z^{-m}P(z^2)$ where P(t) is a polynomial of degree m.

The matrix $R^{(n,m)}$ also can be expressed in terms $e, f, k^{\pm 1}$.

The matrices $R^{(k,l)}$ satisfy the Yang-Baxter equation

$$R_{12}^{(l,m)}(z)R_{13}^{(l,n)}(zw)R_{23}^{(m,n)}(w) = R_{23}^{(m,n)}(w)R_{13}^{(l,n)}(zw)R_{12}^{(l,m)}(z)$$

In addition to this they satisfy identities

$$R^{(l,m)}(z)R^{(m,l)}(z^{-1})^T = s_{ml}(z)s_{ml}(z^{-1})$$

and

$$R_{12}^{(l,m)}(z)^{t_1} = (-1)^l (D_z C^{(m)} \otimes 1) R_{12}^{(l,m)}(zq) (D_z^{-1} C^{(m)})^{-1} \otimes 1$$

where $s_{ml}(z)$ is a Laurent polynomial in z which is easy to compute, $C^{(m)} = P_{12...n}^+ \otimes CP_{12...n}^+$, and we assume that $l \leq m$.

3.6 Higher transfer-matrices

Define $C_q(\widehat{SL}_2)$ -valued matrices

$$\mathfrak{I}^{(m)}(z) = P_{12...n}^{+} \mathfrak{I}_{1}(zq^{\frac{m-1}{2}}) \dots \mathfrak{I}_{m}(zq^{-\frac{m-1}{2}}) P_{12...n}^{+}$$

where $P_{12...n}^+$ is defined above and \Im is the matrix (17).

They satisfy the relations

$$R^{(l,m)}(z)_{12}\mathfrak{I}_1^{(l)}(zw)\mathfrak{I}_2^{(m)}(w)=\mathfrak{I}_2^{(m)}(w)\mathfrak{I}_1^{(l)}(zw)R^{(l,m)}(z)_{12}$$

For non-zero d define the following elements of $C_q(\widehat{SL}_2)$

$$\tau_{\ell}(z) = (\mathrm{id} \otimes tr_{V^{(\ell)}})(\mathfrak{T}^{(\ell)}(z)d^{(l)}) .$$

where $d^{(l)} = diag(d^{l}, d^{l-2}, ..., d^{-l})$ and $d \neq 0$.

The fusion relations for $\Im(z)$ imply the following recursive relations for $\tau_{\ell}(z)$:

$$\tau_1(z)\tau_{\ell}(zq) = \tau_{\ell+1}(z) + \tau_{\ell-1}(zq^2)$$

which can be solved in terms of determinants [5]:

$$\tau_{\ell}(z) = \det \begin{pmatrix} \tau_{1}(z) & 1 & & 0 \\ 1 & \tau_{1}(zq) & \ddots & & \\ & \ddots & \ddots & 1 \\ 0 & & 1 & \tau_{1}(zq^{\ell-1}) \end{pmatrix}.$$

The remarkable fact is that elements $\{\tau_{\ell}(z)\}$ also satisfy another set of relations which also follow from the fusion relations:

$$\tau_{\ell}(zq^{\frac{1}{2}})\tau_{\ell}(zq^{-\frac{1}{2}}) = \tau_{\ell+1}(z)\tau_{\ell-1}(z) + 1. \tag{28}$$

3.7 Local integrable quantum spin Hamiltonians

Transfer-matrices

$$t_m(u) = tr_a(R_{a_1}^{m,m_1}(z/a_1) \dots R_{a_1}^{m,m_1}(z/a_1)d_a^{(l)})$$

form a commuting family of operators in $V^{(m_1)} \otimes \cdots \otimes V^{(m_N)}$. They quantize the generating functions for classical spin chains and can be used to construct local quantum spin chains. Below we outline two common constructions of local Hamiltonians from such transfer-matrices.

3.7.1 Homogeneous SU(2) spin chains

The homogeneous Heisenberg model of spin S corresponds to the choice $m_1 = \cdots = m_N = l$ and $a_N = \cdots = a_1 = 1$. We will denote corresponding transfer matrices as $\tau_m^{(l)}(u)$

In the case m=1, the transfer matrix $t_1^{(1)}(z)$ is

$$t_1^{(1)}(z) = tr_0(R_{0N}(z) \dots R_{01}(z)) \tag{29}$$

where R(z) is the matrix (19).

The linear operator (29) is the transfer matrix of the 6-vertex model [23] [3]. It is also a generating function for local spin Hamiltonians:

$$H_1 = \frac{d}{du} \log(t_1^{(1)}(u))|_{u=0} = \sum_{n=1}^{N} (\sigma_n^x \sigma_{n+1}^y + \sigma_n^y \sigma_{n+1}^y + \Delta \sigma_n^z \sigma_{n+1}^z),$$
(30)

$$H_k = \left(\frac{d}{du}\right)^k \log t_1^{(1)}(u)|_{u=0} = \sum_{n=1}^N H^{(k)}(\sigma_n, \dots, \sigma_{n+k}).$$
 (31)

Here $\sigma^x, \sigma^y, \sigma^z$ are Pauli matrices and σ_n is the collection of Pauli matrices acting nontrivially in the n-th factor of the tensor product.

$$\sigma^x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$
, $\sigma^y = \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}$, $\sigma^z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$. (32)

If l > 1 similar analysis can be done for the transfer-matrix

$$t_l^{(l)}(z) = tr_a(R_{a,1}^{(l,l)}(z) \dots R_{a,N}^{(l,l)}(z))$$

Since $R^{(l,l)}(1) = P$, we have:

$$t_l^{(l)}(1) = tr_a(P_{a1} \dots P_{aN}) = tr_a(P_{12}P_{13} \dots P_{1N}P_{a1}) = P_{12}P_{13} \dots P_{1N}P_{aN}$$

Here we used the identities $P_{a1}A_aP_{a1} = A_1$ and $tr_a(P_{a1}) = I_1$.

The operator $T = t_l^{(l)}(1)$ is the translation matrix:

$$T(x_1 \otimes x_2 \cdots \otimes x_n) = x_N \otimes x_1 \otimes \dots x_{N-1}$$

Differentiating $t_l^{(l)}(z)$ at z=1 we have:

$$t_{l}^{(l)}(1)' = \sum_{i=1}^{N} tr_{a}(P_{a1} \dots P_{ai-1}R_{ai}^{(l,l)}(1)'P_{ai+1} \dots P_{aN}) = T \sum_{i=1}^{N} H_{ii+1}^{(l)}$$

Similarly, taking higher logarithmic derivatives of $t_l^{(l)}(z)$ at z=1 we will have higher local Hamiltonians acting in $(\mathbb{C}^{l+1})^{\otimes N}$:

$$H_k = (z \frac{d}{dz})^k t_l^{(l)}(z)|_{z=1} = \sum_{n=1}^N H_{n,\dots,n+k}^{(k)}.$$

Here the matrix $H^{(k)}$ acts in $(\mathbb{C}^{l+1})^{\otimes k+1}$. The subindices show how this matrix acts in $(\mathbb{C}^{l+1})^{\otimes N}$.

One can show that these local quantum spin chain Hamiltonians in the limit $q\to 1$ and $l\to \infty$ become classical Hamiltonians described in section 2.4, assuming that q^l is fixed.

3.7.2 Inhomogeneous SU(2) spin chains

The construction using degeneration points.

The construction of inhomogeneous local operators is easy to illustrate on the spin chain where the inhomogeneities alternate.

$$t_m(z) = tr_a(R_{a1}^{(m,l_1)}(za^{-1})R_{a2}^{(m,l_2)}(za)\dots R_{a,2N-1}^{(m,l_1)}(za^{-1})R_{a,2N}^{(m,l_2)}(za))$$

Now we have two sublattices and two translation operators

$$T_{even} = P_{24}P_{26} \dots P_{2.2N}, \quad T_{odd} = P_{13}P_{15} \dots P_{1.2N-1}$$

It is easy to find the following special values of the transfer-matrix:

$$t_{l_1}(a) = T^{even} R_{21}^{(l_2, l_1)}(a^{-2}) \dots R_{2N, 2N-1}^{(l_2, l_1)}(a^{-2})$$

$$t_{l_2}(a^{-1}) = R_{12}^{(l_1, l_2)}(a^2) \dots R_{2N-1, 2N}^{(l_1, l_2)}(a^2) T^{odd}$$

These operators commute and

$$t_{l_1}(a)t_{l_2}(a^{-1}) = T^{even}T^{odd}$$

$$t_{l_1}(a)t_{l_2}(a^{-1})^{-1} = T^{even}(T^{odd})^{-1}$$

$$R_{2,2N-1}^{(l_2,l_1)}(a^{-2})R_{4,1}^{(l_2,l_1)}(a^{-2})\dots R_{2N,2N-3}^{(l_2,l_1)}(a^{-2})R_{2N-1,2N}^{(l_1,l_2)}(a^{-2})\dots R_{1,2}^{(l_1,l_2)}(a^{-2})$$

$$(33)$$

Taking logarithmic derivatives of $t_{l_1}(z)$ at z=a and of $t_{l_2}(z)$ at $z=a^{-1}$ we again will have local operators, for example:

$$z\frac{d}{dz}\log t_{l_1}(z)|_{z=a} = \sum_{n=1}^{N} R_{2n+1,2n}^{-1}(a^2)R'_{2n+1,2n}(a^2) + \sum_{n=1}^{N} R_{2n+1,2n}^{-1}(a^2)P_{2n+1,2n-1}R'_{2n+1,2n-1}(1)R_{2n+1,2n}(a^2)$$
(34)

These Hamiltonians in the semiclassical limit reproduce inhomogeneous classical spin chains described earlier.

4 The spectrum of transfer-matrices

4.1 Diagonalizability of transfer-matrices

Assume that q is real. Let $t(u)^*$ be the Hermitian conjugation of t(u) with respect to the standard Hermitian scalar product on $(\mathbb{C}^2)^{\otimes N}$. It is easy to prove, using the identities for R(u) that

$$t(z|a_1,\ldots,a_N)^* = (-1)^N t(\overline{z}^{-1}q^{-1}|\overline{a_1}^{-1}\ldots\overline{a_N}^{-1})$$

where \overline{z} is the complex conjugate to z.

Because t(z) is the commutative family of operators, the operators t(z) is normal when $\overline{a_i} = a_i^{-1}$. Therefore for these values of a_i it is diagonalizable. Since t(z) is linear (up to a scalar factor) in a_i^2 , this imply that t(z) is diagonalizable for all generic complex values of a_i , and for the same reasons for all generic complex values of q.

4.2 Bethe ansatz for sl_2

In this section we will recall the algebraic Bethe ansatz for the inhomogeneous finite dimensional spin chain.

The quantum monodromy matrix for such spin chain is:

$$T(z) = \mathcal{L}_1^{(m_1)}(z/a_1) \dots \mathcal{L}_N^{(m_N)}(z/a_N) D$$
 (35)

where

$$D = \left(\begin{array}{cc} Z & 0\\ 0 & Z^{-1} \end{array}\right)$$

It is convenient to write it as

$$T(z) = \begin{pmatrix} A(z) & B(z) \\ C(z) & D(z) \end{pmatrix}$$

In the basis $e_1 \otimes e_1, e_1 \otimes e_2, e_2 \otimes e_1, e_2 \otimes e_2$ of the tensor product $\mathbb{C}^2 \otimes \mathbb{C}^2$ we

$$T_1(zw)T_2(w) = \left(\begin{array}{cccc} A(zw)A(w) & A(zw)B(w) & B(zw)A(w) & B(zw)B(w) \\ A(zw)C(w) & A(zw)D(w) & B(zw)C(w) & B(zw)D(w) \\ C(zw)A(w) & C(zw)B(w) & D(zw)A(w) & D(zw)B(w) \\ C(zw)C(w) & C(zw)D(w) & D(zw)C(w) & D(zw)D(w) \end{array} \right)$$

Writing the R-matrix in the tensor product basis as in (19)

$$R(z) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & f(z) & g(z)z^{-1} & 0 \\ 0 & g(z)z & f(z) & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

the commutation relations (16) produce the following relations between A and B and D and B:

$$A(z)B(v) = \frac{1}{f(vz^{-1})}B(v)A(z) - \frac{g(vz^{-1})zv^{-1}}{f(vz^{-1})}B(z)A(v)$$

$$D(z)B(v) = \frac{1}{f(zv^{-1})}B(v)D(z) - \frac{g(zv^{-1})zv^{-1}}{f(zv^{-1})}B(z)D(v)$$

where
$$f(z) = \frac{z-z^{-1}}{zq-z^{-1}q^{-1}}, g(z) = \frac{q-q^{-1}}{zq-z^{-1}q^{-1}}.$$
 The *L*-operators act on the vector

$$\Omega = v_0^{(m_1)} \otimes v_0^{(m_2)} \otimes \cdots \otimes v_0^{(m_N)}$$

in a special way:

$$\mathcal{L}_{i}(z)\Omega = \begin{pmatrix} (zq^{\frac{m_{i}+1}{2}} - z^{-1}q^{-\frac{m_{i}+1}{2}})\Omega & * \\ 0 & (zq^{-\frac{m_{i}-1}{2}} - z^{-1}q^{\frac{m_{i}-1}{2}})\Omega \end{pmatrix}$$

From here it is clear that Ω is an eigenvector for operators A and D and that C annihilates it:

$$T(z)\Omega = \begin{pmatrix} \alpha(z)\Omega & * \\ 0 & \delta(z)\Omega \end{pmatrix}$$

where

$$\alpha(z) = Z \prod_{i=1}^{N} (z a_i^{-1} q^{\frac{m_i+1}{2}} - z^{-1} a_i q^{-\frac{m_i+1}{2}})$$

$$\delta(z) = Z^{-1} \prod_{i=1}^{N} \left(z a_i^{-1} q^{-\frac{m_i - 1}{2}} - z^{-1} a_i q^{\frac{m_i - 1}{2}} \right)$$

The details of proof of the following construction of eigenvectors can be found in [14].

Theorem 1. The following identity holds

$$(A(z) + D(z))B(v_1) \dots B(v_n)\Omega = \Lambda(z|\{v_i\})B(v_1) \dots B(v_n)\Omega$$

where

$$\Lambda(z|\{v_i\}) = \alpha(z) \prod_{i=1}^{n} \frac{v_i z^{-1} q - v_i^{-1} z q^{-1}}{v_i z^{-1} - v_i^{-1} z} + \delta(z) \prod_{i=1}^{n} \frac{v_i^{-1} z q - v_i z^{-1} q^{-1}}{v_i^{-1} z - v_i z^{-1}}$$
(36)

if the numbers v_i satisfy the Bethe equations:

$$\prod_{\alpha=1}^{N} \frac{v_i a_{\alpha}^{-1} q^{\frac{m_{\alpha}+1}{2}} - z^{-1} a_{\alpha} q^{-\frac{m_{\alpha}+1}{2}}}{v_i a_{\alpha}^{-1} q^{-\frac{m_{\alpha}-1}{2}} - z^{-1} a_{\alpha} q^{\frac{m_{\alpha}-1}{2}}} = -Z^2 \prod_{j=1}^{n} \frac{v_i v_j^{-1} q - v_i^{-1} v_j q^{-1}}{v_i v_j^{-1} q^{-1} - v_i^{-1} v_j q}$$
(37)

Note that the formula for the eigenvalues in terms of solutions to Bethe equations is a rational function. Bethe equations can be regarded as conditions

$$res_{z=v_i}\Lambda(z|\{v_i\})=0$$

This agrees with the fact that t(z) is a commuting family of operators which has no poles at finite z.

4.3 The completeness of Bethe vectors

The next step is to establish whether the construction outlined above all eigenvectors. We will focus here on the spin chain of spin 1/2.

Assume that q, e^{2H} , and inhomogeneities a_i are generic. Let us demonstrate that the vectors

$$B(v_1) \dots B(v_n) \Omega$$
 (38)

where v_i are solutions to Bethe equations give all 2^N eigenvectors of the transfermatrix.

4.3.1

Consider the limit of (38) when $a_N \to \infty$.

Assume that v is fixed and $a_N \to \infty$. From the definition of B(v) we have:

$$B(v) = a_N q^{-\frac{1}{2}} v^{-1} (\tilde{A}(v) \otimes f - \tilde{B}(v) \otimes K) (1 + o(1))$$

where $\tilde{A}(v)$, $\tilde{B}(v)$ are elements of the quantum monodromy matrix (35) with only N-1 first factors.

On the other hand if $a_N \to \infty$ and $v \to \infty$ such that $v = wa_N$ and w is finite the asymptotic is different:

$$B(v) = w^{-1}q^{-\frac{1}{2}} \prod_{n=1}^{N} (wa_{N}a_{n}^{-1}q^{\frac{1}{2}})k \otimes \cdots \otimes k \otimes f(1+o(1))$$

From here we obtain the asymptotic of Bethe vectors when all v_i are fixed and $a_N \to \infty$

$$B(v_1) \dots B(v_n) \Omega_N \to q^{\frac{m_N+1}{2}n} (-a_N q^{\frac{1}{2}})^n \prod_{i=1}^n v_i^{-1}$$

$$(\tilde{B}(v_1) \dots \tilde{B}(v_n) \Omega_{N-1} \otimes v_0^{(m_N)} - \sum_{i=1}^n q^{-\frac{m_N+1}{2} - i + 1}$$

$$\tilde{B}(v_1) \dots \tilde{A}(v_i) \dots \tilde{B}(v_n) \Omega_{N-1} \otimes f v_0^{(m_N)}) (1 + o(1)). \quad (39)$$

Similarly, when v_1, \ldots, v_{n-1} are fixed and $a_N \to \infty$ such that $v_n = wa_N$ we have

$$B(v_1) \dots B(v_n) \Omega_N \to q^{\frac{m_N+1}{2}(n-1)-n} (-a_N q^{\frac{1}{2}})^{n-1} \prod_{i=1}^{n-1} v_i^{-1} q^{\frac{m_i}{2}}$$

$$\tilde{B}(v_1) \dots \tilde{B}(v_{n-1}) \Omega_{N-1} \otimes f v_0^{(m_N)} (1 + o(1)) \quad (40)$$

4.3.2

Solutions to (37) have the following possible asymptotic when $a_N \to \infty$:

- 1. For all $j=1,\ldots,N$, $\lim_{a_N\to\infty}v_j=v_j'$ where $\{v_j'\}$ is a solution to the Bethe system for the spin chain of length N-1 with inhomogeneities a_1,\ldots,a_{N-1} and Z.
- 2. For one of v_j 's, say for v_n we have $v_n = a_N w + O(1)$ and for others $\lim_{a_N \to \infty} v_j = v_j'$ where $\{v_j'\}$ is a solution to the Bethe system for the spin chain of length N-1 with inhomogeneities a_1, \ldots, a_{N-1} and Zq^{-1} . From the Bethe equation for v_n we have

$$w^2 = \frac{1 - Z^2 q^{-N+2n}}{q^2 - Zq^{-N+2n}}$$

3. More then one of v_i is proportional to a_N .

Using induction and the asymptotic of Bethe vectors (39) and (40) it is easy to show that only first two options describe the spectrum of the spin 1/2 transfer-matrix. Similar arguments were used in [18] to prove the completeness of Bethe vectors in an SL_n spin chain.

This implies immediately that there are $\binom{N}{n}$ Bethe vectors for each $0 \le n \le N$. And that the total number of Bethe vectors is

$$2^N = \sum_{n=0}^N \left(\begin{array}{c} N \\ n \end{array} \right)$$

Other solutions to Bethe equations describe eigenvectors in infinite dimensional representations of quantized affine algebra with the same weights. They do not correspond to any eigenvectors of the inhomogeneous spin 1/2.

4.3.3

For special values of a_{α} the solutions to the Bethe equations may degenerate (a level crossing may occur in the spectrum of t(z)). In this case the Bethe ansatz should involve derivatives of vectors (38).

5 The thermodynamical limit

The procedure of "filling Dirac seas" is a way to construct physical vacua and the eigenvalues of quantum integrals of motion in integrable spin chains solvable by Bethe ansatz.

To be specific, consider the homogenous spin chain of spins 1/2. Let $H_1, H_2, ...$ be quasilocal Hamiltonians described in the section 3.7.1 with $q = \exp(\eta)$ for some real η .

Take the linear combination

$$H(\lambda) = \sum_{k} H_k \lambda_k \tag{41}$$

This operator is bounded. Let $\Omega_N(\lambda)$ be its normalized ground state. As $N \to \infty$, matrix elements $(\Omega_N, a\Omega_N)$ converges to the state ω_λ on the inductive limit of the algebra of observables. The action of local operators on ω_λ generate the Hilbert space \mathcal{H} .

Since the eigenvalues of coefficients of t(u) can be computed in terms of solutions to Bethe equations, the spectrum of these operators in the large N is determined by the large N asymptotic of solutions to Bethe equations.

The main assumption in the analysis of the Bethe equations in the limit $N \to \infty$ is that the numbers $\{v_{\alpha}^{(0)}\}^{-1}$ are distributed along the real line with some density $\rho(u)$. The intervals where $\rho(u) \neq 0$ are called Dirac seas. For Hermitian Hamiltonian (41) there is strong evidence that Dirac seas is a finite collction of intervals $(B_1^+, B_1^-), \ldots, (B_n^+, B_n^-)$. Here numbers B_{α}^{\pm} are boundaries of Dirac seas. We assume they are increasing from left to right. The boundaries of Dirac seas are uniquely determined by $\{\lambda_l\}$.

A solution to the Bethe equations is said to contain an m-string, when as $N \to \infty$, there is a subset of $\{v_i\}$ of the form

$$v^{(m)} + i\frac{\eta}{2}m, v^{(m)} + i\frac{\eta}{2}(m-2), \dots, v^{(m)} - i\frac{\eta}{2}(m-2), v^{(m)} - i\frac{\eta}{2}m.$$

with some real $v^{(m)}$.

The excitations over the ground states can be of the following types:

• A hole in the Dirac sea (B_k^+, B_k^-) correspond to the solution to Bethe equations which has one less number v_i , and as $N \to \infty$ the remaining v_i "fill" the same Dirac seas with the densities deformed by the fact that one of the numbers $\{v_{\alpha}^{(0)}\}$ is missing and other are "deformed" by

 $^{^1 {\}rm solutions}$ to the Bethe equations corresponding to the minimum eigenvalue of $H(\lambda)$

the missing one. The number which is "missing" is a state with a hole is the "rapidity" $v \in (B_k^+, B_k^-)$ of the hole.

- Particles correspond to "adding" one real number to the collection $\{v_{\alpha}^{(0)}\}$).
- m-strings, m > 1 (corresponding to adding one m-string solution to the collection $\{v_{\alpha}^{(0)}\}$).

There are convincing arguments, that the Fock space of the system with the Hamiltonian (41) has the following structure. It has a vacuum state \mathcal{O}_{λ} corresponding to the solution of the Bethe equations with the minimal eigenvaue of $H(\lambda)$. Excited states are eigenvectors of the Hamiltonian (and of all other integrals) which correspond to solutions of Bethe equations with finitely many holes, particles, and m-strings. It has the following structure

$$\mathcal{H}(\{B_i^+, B_i^-\}_{i=1}^k) = \bigoplus_{\substack{N_h \ge 0, N_p \ge 0, N \ge 0 \ n_1 + \dots + n_k = N_h, N_p \\ \\ \cdot \bigotimes_{i=1}^k L_2^{\operatorname{symm}}(I_1^{+ \times n_1} \times \dots I_k^{+ \times n_k} \times I^{N_p} \times S^{1^N})$$

Here we used the notation $I_l^+ = (B_l^+, B_l^-), I_l^- = (B_{l-1}^+, B_l^-)$, where $B_0^+ = -\pi$, and $B_{k+1}^- = \pi$; n_k is the number of holes in the Dirac sea $(B_k^+, B_k^-), N_p$ is the number of particles; I is the complement to the Dirac seas, N is the number of strings with $m \geq 2$. The symbol "symm" means certain symmetrization procedure which we will not discuss here (see, for example, [17] for a discussion of the aniferromagnetic ground state).

Varying $\{\lambda_k\}$, or equivalently, positions $\{B_k^{\pm}\}$ of Dirac seas we obtain a "large" part of the space of states of the spin chain in the limit $N \to \infty$: $(\mathbb{C}^2)^{\otimes N}$ in the limit $N \to \infty$ into the direct integral of separable Hilbert spaces:

$$(\mathbb{C}^2)^{\otimes N} \to \bigoplus_{k>0} \int_{[-\pi,\pi]^{\times 2k}}^{\oplus} \mathcal{H}(\{B_i^+, B_i^-\}_{i=1}^k)$$
 (42)

6 The 6-vertex model

6.1 The 6-vertex configurations and boundary conditions

The 6-vertex model is a model is statistical mechanics where states are configurations of arrows on a square planar grid, see an example on Fig. 5. The weights are assigned to vertices of the grid. They depend on the arrows on edges surrounding the vertex non-zero weights correspond to the configurations on Fig. 1, to configurations where the number of incoming arrows in equal to the number of outgoing arrows. This is also known as the ice rule [24].

Each configuration of arrows on the lattice can be equivalently described as the configuration of "thin" and "thick" edges (or "empty" and "occupied"

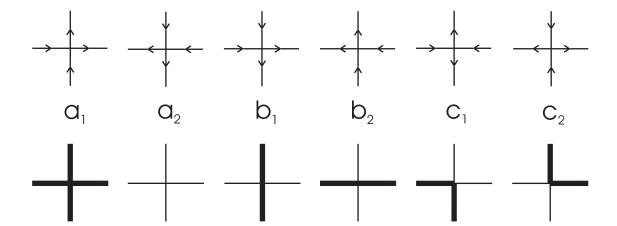


Figure 1: The 6 types of vertices and the corresponding thin and thick edges configurations.

edges) as it is shown on figure 1. There should be an even number of thick edges at each vertex as a consequence of the ice rule.

The thick edges form paths going from NorthWest (NW) to SouthEast (SE). We assume that when there are 4 think edges meeting at a vertex, the corresponding paths meet at this point and then are going apart. So, equivalently, configurations of the 6-vertex model can be regarded as configurations of paths going from NW to SE satisfying the rules from Fig. 1¹.

6.2 Boundary conditions

It is natural to consider the 6-vertex model on surface grids.

If the surface is a domain on a plane we will say that an edge is *outer* if it intersects the boundary of a domain. We assume that the boundary is chosen such that it intersects each edge at most once. Outer edges are attached to a 4-valent vertex by one side and to the boundary by the other side.

Fixed boundary conditions means that fixing the 6-vertex configurations on outer edges. An example of fixed boundary conditions known as domain wall (DW) boundary conditions on a square domain is shown on fig. 5.

We will be interested in three types of boundary conditions:

- A domain (connected simply connected on a plane) with fixed boundary conditions, see Fig. 2. We will also call this Dirichlet boundary conditions.
- A cylinder with fixed boundary conditions, see Fig. ??. This case can

¹One can consider such configurations on any 4-valent graph. But only for special graphs and special Boltzmann weights one can compute the partition function pe site.



Figure 2: A domain, connected, simply-connected.

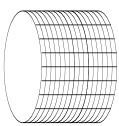


Figure 3: Cylindric boundary conditions.

be regarded as a domain with states on outer edges of two sides being identified and with fixed boundary conditions on other sides.

• Identification of states on outer edges of opposite sides of a rectangle gives the states for the 6-vertex model on a torus, see Fif. 4. It is also known as the 6-vertex model with periodical boundary conditions.

6.3 The partition function and local correlation functions

To each configuration a_1 , a_2 , b_1 , b_2 , c_1 , and c_2 on Fig. 1 we assign Boltzmann weights which we denote by the same letters. The physical meaning of a Boltzmann weight is $\exp(-\frac{E}{T})$, where E is the energy of a state and T is the temperature (in appropriate units), so all numbers a_1 , a_2 , b_1 , b_2 , c_1 , and c_2 should be positive.

The weight of the configuration is the product of weights corresponding to vertices inside the domain of weights assigned to each vertex by the 6-vertex rules.

The 6-vertex model is called *homogeneous* if the weight assigned to a vertex depends only on the configuration of arrows on adjacent edges and not on the vertex itself.

When the weights also depend on the vertex the model is called inhomogeneous.

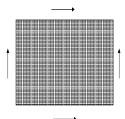


Figure 4: Toric boundary conditions.

The partition function is the sum of weights of all states of the model

$$Z = \sum_{\text{states vertices}} w(\text{vertex}),$$

where w(vertex) is the weights of a vertex assigned according to Fig. 1.

Weights of states define the probabilistic measure on the set of states of the 6-vertex model. The probability of a state is given by the ratio of the weight of the state to the partition function of the model

$$P(state) = \frac{\prod_{\text{vertices}} w(\text{vertex})}{Z}.$$
 (43)

The characteristic function of an edge e is the function defined on the set of 6-vertex states

$$\sigma_e(state) = \left\{ \begin{array}{ll} 1, & e \text{ is occupied by a path,} \\ 0, & \text{otherwise.} \end{array} \right.$$

A *local correlation function* is the expectation value of the product of such characteristic functions with respect to the measure (43):

$$\langle \sigma_{e_1} \sigma_{e_2} ... \sigma_{e_n} \rangle = \sum_{states} P(state) \prod_{i=1}^n \sigma_{e_i}(state).$$

It is convenient to write the Boltzmann weights in exponential form

$$\begin{aligned} a_1 &= ae^{H+V}, & a_2 &= ae^{-H-V}, \\ b_1 &= be^{+H-V}, & b_2 &= be^{-H+V}, \\ c_1 &= ce^{-E}, & c_2 &= ce^{E}, \end{aligned}$$

From now on we will assume that E=0. If the weight are homogenous (do not depend on a vertex), local correlation functions for a domain, cylinder or torus do not depend on E. Also, the parameters H and V have a clear physical meaning, they can be regarded as horizontal and vertical electric fields. Indeed,

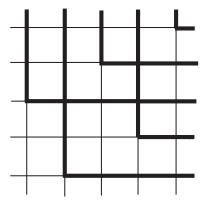


Figure 5: A possible configuration of paths on a 5×5 square grid for the DW boundary conditions.

if E = 0 the weight of the state can be written as

$$w(S) = \prod_{v \in vertices} w(v|S)$$

$$\exp(\sum_{e \in E_h} \sigma_e(S)(H(e_+) + H(e_-))/2 + \sum_{e \in E_v} \sigma_e(S)(V(e_+) + V(e_-))/2) \quad (44)$$

Here S is a state of the model, E_h is a set of horizontal edges and E_v is the set of vertical edges, w(v|S) is the weight of the vertex v in the state S where $a_1 = a_2 = a$ and $b_1 = b_2 = b$. The symbol $\sigma_e(S)$ is the characteristic function of e: $\sigma_e(S) = 1$ if the arrow pointing up or to the left, and $\sigma_e(S) = -1$ if the arrow is pointing down or to the right.

For a given domain let us chose its boundary edge and enumerate all other boundary edges counter-clock wise. The partition function for a domain for various fixed boundary conditions can be considered as a vector in $(\mathbb{C}^2)^{\otimes N}$ where the factors in the tensor product counted from left to right correspond to enumerated boundary vertices.

Similarly, the partition function for a (vertical) cylinder of size $N \times M$ (horizontal, vertical) can be regarded as a linear operators acting in $(\mathbb{C}^2)^{\otimes N}$ where the factors in the tensor product correspond to states on boundary edges.

The partition function for the *torus* of size $N \times M$ is a number and it can be regarded as a the trace of the partition for the vertical cylinder of size $N \times M$ over the states on its horizontal sides, i.e. over $(\mathbb{C}^2)^{\otimes N}$. It can also be regarded as trace of the partition for the horizontal cylinder of size $M \times N$ over the states on its vertical sides, i.e. over $(\mathbb{C}^2)^{\otimes M}$. The result is an identity which we will discuss later.

6.4 Transfer-matrices

Let is write the matrix of Boltzmann weights for a vertex as the 4×4 matrix acting in the tensor product of spaces of states on adjacent edges.

Let e_1 be the vector corresponding to the arrow pointing up on a vertical edge, and left on a horizontal edge. Let e_2 be the vector corresponding to the arrow pointing down on a vertical edge and right on a horizontal edge.

The matrix of Boltzmann weights with zero electric fields acts as

$$Re_1 \otimes e_1 = ae_1 \otimes e_1 \tag{45}$$

$$Re_1 \otimes e_2 = be_1 \otimes e_2 + ce_2 \otimes e_1$$
 (46)

$$Re_2 \otimes e_1 = be_2 \otimes e_1 + ce_1 \otimes e_2$$
 (47)

$$Re_2 \otimes e_2 = ae_2 \otimes e_2$$
 (48)

In the tensor product basis $e_1 \otimes e_1, e_1 \otimes e_2, e_2 \otimes e_1, e_2 \otimes e_2$ it is the 4×4 matrix

$$\overline{R} = \begin{pmatrix} a & 0 & 0 & 0 \\ 0 & b & c & 0 \\ 0 & c & b & 0 \\ 0 & 0 & 0 & a \end{pmatrix}$$

$$\tag{49}$$

The 6-vertex rules imply that the operator R commutes with the operator representing the total number of thick vertical edges, i.e.

$$[D^H \otimes D^H, \overline{R}] = 0$$

where

$$D^H = \begin{pmatrix} e^{H/2} & 0 \\ 0 & e^{-H/2} \end{pmatrix}.$$

The row-to-row transfer-matrices with open boundary conditions also known as the (quantum) *monodromy matrix* is defined as

$$T_a = D_a^{H(a,1)} R_{a1} D_a^{H(a,1)} \dots D_a^{H(a,1)} R_{aN}$$

It acts in the tensor product $\mathbb{C}^2_a \otimes \mathbb{C}^2_1 \otimes \cdots \otimes \mathbb{C}^2_N$ of spaces corresponding to horizontal edges and vertical edges. Each matrix R_{ai} is of the form (??), it acts trivially (as the identity matrix) in all factors of the tensor product except a and i. In the inhomogeneous case matrix elements of \overline{R}_{ai} depend on i.

A matrix element of T is the partition function of the 6-vertex model on a single row with fixed boundary conditions.

Define operators

$$D^{(a)} = D^{V(a,1)} \otimes \cdots \otimes D^{V(a,N)}$$
$$D_a^H = 1 \otimes \cdots \otimes D^H \otimes \cdots \otimes 1$$

The row-to-row transfer-matrix corresponding to the cylinder with a single horizontal row a with with electric field H(a,i) applied to the i-th horizontal edge of the a-th horizontal line is the following trace

$$t_a = tr_a(T_a) = tr(D_a^{H(a,1)}R_{a1}\dots D_a^{H(a,N)}R_{aN})$$

It is an operator acting in $(\mathbb{C}^2)^{\otimes N}$. Its matrix element is the partition function of the 6-vertex model on the cylinder with a single row with fixed boundary conditions on vertical edges.

The partition function of an inhomogeneous 6-vertex on a cylinder of height M with fixed boundary condition on outgoing vertical edges is a matrix element of the linear operator

$$Z^{(C)} = D^{(M)}t_M \dots D^{(1)}t_1$$

where

$$D^{(a)} = D^{V(a,1)} \otimes \cdots \otimes D^{V(a,N)}$$

The partition function for the torus with N columns and M rows is the trace of the partition function for the cylinder

$$Z_{N,M}^{(T)} = tr_{(\mathbb{C}^2)^{\otimes N}}(D^{(M)}t_M \dots D^{(1)}t_1)$$

Using the 6-vertex rules this trace can be transformed to

$$Z_{N,M}^{(T)} = tr_{(\mathbb{C}^2)^{\otimes N}}(t_M^{(H_M)} \dots t_1^{(H_1)}(D_1^{V_1} \otimes \dots \otimes D_N^{V_N}))$$

where $H_a = \sum_{i=1}^{N} H_{ai}$ and $V_i = \sum_{a=1}^{M} V_{ai}$ and

$$t^{(H)} = tr_a(R_{a1} \dots R_{aN} D_a^H)$$

The partition function for a generic domain does not have a natural expression in terms of a transfer-matrix. However, it is possible in few exceptional cases, such as domain wall boundary conditions on a square domain, see for example [16]. and references therein.

6.5 The commutativity of transfer-matrices and positivity of weights

6.5.1 Commutativity of transfer-matrices

Baxter discovered that matrices of the form (??) acting in the tensor product of two two-dimensional spaces satisfy the equation

$$R_{12}R'_{13}R''_{23} = R''_{23}R'_{13}R_{12} (50)$$

if

$$\frac{a^2+b^2-c^2}{2ab} = \frac{{a'}^2+{b'}^2-{c'}^2}{2a'b'} = \frac{{a''}^2+{b''}^2-{c''}^2}{2a''b''}$$

This parameter is denoted by Δ :

$$\Delta = \frac{a^2 + b^2 - c^2}{2ab}$$

If each factor in monodromy matrices $T'_a = R'_{a1} \dots R'_{aN}$ and $T''_b = R''_{a1} \dots R''_{aN}$ have the same value of Δ , the equation (50) implies that they these monodromy matrices satisfy the relation

$$R_{ab}T'_aT''_b = T''_bT'_aR_{ab}$$

in $V_a \otimes V_b \otimes V_1 \otimes \cdots \otimes V_N$.

If R is invertible, this relation implies that row-to-row transfer-matrices with periodic boundary conditions commute:

$$t' = tr_a(T_a'D_a^H), \quad t'' = tr_b(T_b''D_b^H), \quad [t', t''] = 0$$

It is easy to recognize that t is exactly the generating function for commuting family of local Hamiltonians for spin chains constructed earlier. Thus, the problem of computing the partition function for periodic and cylindrical boundary conditions for the 6-vertex model is closely related to finding the spectrum of Hamiltonians for integrable spin chains.

6.5.2 The parametrization

The set of positive triples of real numbers a:b:c (up to a common multiplier) with fixed values of Δ has the following parametrization [3].

1. When $\Delta > 1$ there are two cases.

If a > b + c, the Boltzmann weights a, b, and c can be parameterized as

$$a = r \sinh(\lambda + \eta), \quad b = r \sinh(\lambda), \quad c = r \sinh(\eta)$$

with $\lambda, \eta > 0$.

If b > a + c, the Boltzmann weights can be parameterized as

$$a = r \sinh(\lambda - \eta), \quad b = r \sinh(\lambda), \quad c = r \sinh(\eta)$$

with $0 < \eta < \lambda$. For both of these parameterizations of weights $\Delta = \cosh(\eta)$.

2. When $-1 < \Delta \le 0$

$$a = r \sin(\lambda - \gamma), \quad b = r \sin(\lambda), \quad c = r \sin(\gamma),$$

where $0 < \gamma < \pi/2$, $\gamma < \lambda < \pi/2$, and $\Delta = -\cos \gamma$.

3. When $0 \le \Delta < 1$

$$a = r \sin(\gamma - \lambda), \quad b = r \sin(\lambda), \quad c = r \sin(\gamma),$$

where $0 < \gamma < \pi/2$, $0 < \lambda < \gamma$, and $\Delta = \cos \gamma$.

4. When $\Delta < -1$ the parametrization is

$$a = r \sinh(\eta - \lambda), \quad b = r \sinh(\lambda), \quad c = r \sinh(\eta),$$

where $0 < \lambda < \eta$ and $\Delta = -\cosh \eta$.

We will write a = a(u), b = b(u), c = c(u) assuming this parameterizations.

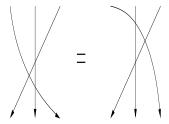


Figure 6: The Yang-Baxter equation.

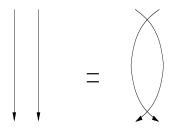


Figure 7: The 'unitarirty'.

6.5.3 Topological nature of the partition function of the 6-vertex model

Fix a domain and a collection of simple non-selfintersecting oriented curves with simple (transversive) intersections. The result is a 4-valent graph embedded into the domain. Fix 6-vertex states (arrows) at the boundary edges of this graph. Such graph connects boundary points, and defines a perfect matching between boundary points.

The 6-vertex rules define the partition function on such graph. The Yang-Baxter relation implies the invariance with respect to the two moves shown of Fig. 6, Fig. 7. Because of this, the partition function of the 6-vertex model depends only on the connection pattern between boundary points, i.e. it depends only on the perfect matching on boundary points induced by the graph.

The 'unitarity' relation involves the inverse to R, and therefore does not preserve the positivity of weights. But if it is used "even" number of times it gives the equivalence of partition functions with positive weights. For example it can be used to 'permute' the rows in case of cylindrical boundary conditions.

6.5.4 Inhomogeneous models with commuting transfer-matrices

From now on we will focus on the 6-vertex model in constant electric fields. If Boltzmann weights of the 6-vertex model have special inhomogeneity $a_{ij} = a(u_i - w_j)$, $b_{ij} = b(u_i - w_j)$, $c_{ij} = c(u_i - w_j)$ the partition function of the 6-vertex

model on the torus is

$$Z_{N,M}^{(T)}(\{u\},\{w\}|H,V) = Tr_{\mathcal{H}_N}(t(u_1)\dots t(u_M)(D^{NV}\otimes\dots\otimes D^{NV}))$$
 (51)

where $\mathcal{H}_N = (\mathbb{C}^2)^{\otimes N}$ and $t(u) = tr_a(T_a(u))$

$$T_a(u) = R_{a1}(u - w_1) \dots R_{aN}(u - w_N) D^{NH}$$
(52)

Because the R-matrix satisfies the Yang-Baxter equation we have

$$R_{ab}(u-v)T_a(u)T_b(v) = T_b(v)T_a(u)R_{ab}(u-v)$$

As a corollary, traces of these matrices commute:

$$[t(u), t(v)] = 0$$

and as we have seen the previous sections their spectrum can be described explicitly by the Bethe ansatz.

Notice that positivity of weights restricts possible value of inhomogeneities. For example when $\Delta > 1$ and a > b + c we should have $-u < w_i < u$.

6.5.5

For a diagonal matrix d such that $[d \otimes 1 + 1 \otimes d, R(u)] = 0$ define

$$R^d(u) = (e^{ud} \otimes 1)R(u)(e^{-ud} \otimes 1)$$

It is clear that

$$tr(R_{a1}^d(u-w_1)\dots R_{aN}^d(u-v_N)D^{NH}) = Utr(R_{a1}(u-w_1)\dots R_{aN}(u-v_N)D^{NH})U^{-1}$$

where $U = \exp(-\sum_{i=1}^N w_i d_i)$.

In particular the partition function for a torus with weights given by R(u) and with weights given by $R^d(u)$ are the same.

6.5.6

Let u_1, \ldots, u_N be parameters of inhomogeneities along horizontal directions, and w_1, \ldots, w_M be inhomogeneities along vertical directions. The partition function (??) have the following properties:

- $Z_{NM}^{(T)}(\{u\},\{w\}|H,V)$ is a symmetric function of u and w.
- It has a form $\prod_{i=1}^N e^{-Mu_i} \prod_{i=1}^M e^{-Nw_i} P(\{e^{2u}\}, \{e^{2w}\})$ where P is a polynomial of degree M in each e^{u_i} and of degree N is each e^{w_j} .
- It is a function of $u_i w_j$.
- It satisfies the identity

$$Z_{N,M}^{(T)}(\{u\},\{w\}|H,V) = Z_{M,N}^{(T)}(\{w\},\{h-u\}|V,H)$$
 (53)

where $h = \eta$ or γ depending on the regime. This identity correspond to the "rotation" of the torus by 90 degrees and is known as "crossing-symmetry" or "modular identity".

7 The 6-vertex model on a torus in the thermodynamic limit

7.1 The thermodynamic limit of the 6-vertex model for the periodic boundary conditions

By the thermodynamical limit here we will mean here the large volume limit, when $N, M \to \infty$.

The free energy per site in this limit is

$$f = -\lim_{N,M \to \infty} \frac{\log(Z_{N,M})}{NM}$$

where $Z_{N,M}$ is the partition function with the periodic boundary conditions on the rectangular grid $L_{N,M}$. It is a function of the Boltzmann weights and magnetic fields.

For generic H and V the 6-vertex model in the thermodynamic limit has the unique translational invariant Gibbs measure with the slope (h, v):

$$h = -\frac{1}{2}\frac{\partial f}{\partial H} + \frac{1}{2}, \quad v = -\frac{1}{2}\frac{\partial f}{\partial V} + \frac{1}{2}.$$
 (54)

This Gibbs measure defines local correlation functions in the thermodynamical limit The parameter

$$\Delta = \frac{a^2 + b^2 - c^2}{2ab}.$$

defines many characteristics of the 6-vertex model in the thermodynamic limit.

7.2 The large N limit of the eigenvalues of the transfermatrix

The row-to-row transfer-matrix for the homogeneous 6-vertex model on a lattice with periodic boundary condition with rows of length N is

$$t(u) = tr_a(R_{a1}(u) \dots R_{aN}(u)e^{H\sigma^z}) \exp(V \sum_{a=1}^{N} \sigma_a^z)$$

According to (36) and (37), the eigenvalues of this linear operator are:

$$\Lambda_{\{v_i\}} = a^N e^{NH} \prod_{i=1}^n \frac{v_i z^{-1} q - v_i^{-1} z q^{-1}}{v_i z^{-1} - v_i^{-1} z} + b^N e^{-NH} \prod_{i=1}^n \frac{v_i^{-1} z q - v_i z^{-1} q^{-1}}{v_i^{-1} z - v_i z^{-1}}$$
(55)

where $0 \le n \le N$ and z, q are parameterizing a, b, c as $a = r(zq - zq^{-1}, b = r(z - z^{-1}), c = r(q - q^{-1})$. The numbers v_i are solutions to the Bethe equations:

$$\left(\frac{v_i q - v_i^{-1} q^{-1}}{v_i - v_i^{-1}}\right)^N = -e^{-2H} \prod_{j=1}^n \frac{v_i v_j^{-1} q - v_i^{-1} v_j q^{-1}}{v_i v_j^{-1} q^{-1} - v_i^{-1} v_j q}$$
(56)

As for the corresponding spin chains it is expected that the numbers v_i corresponding to the largest eigenvalue concentrate, when $N \to \infty$, on a contour in a complex plane with the finite density. The Bethe equations provide a linear integral equation for this density. This conjecture is supported by the numerical evidence and it is proven in some special cases, for example when $\Delta = 0$.

The partition function for the homogeneous 6-vertex model on an $N \times M$ lattice with periodic boundary conditions is

$$Z_{N,M} = \sum_{\alpha} \Lambda_{\alpha}^{(N)M} \tag{57}$$

where α parameterize eigenvalues of t(u).

Let ω_N be the eigenvector of t(u) corresponding to the maximal eigenvalue. The sequence of vectors $\{\Omega_N\}$ as $N \to \infty$ defines the Hilbert space of pure states for the infinite system. Let Λ_0 be the largest eigenvalue of t(u). According to the main conjecture about that the largest eigenvalue correspond to numbers v_i filling a contour in a complex plane as N, the largest eigenvalue has the following asymptotic:

$$\Lambda_0^{(N)} = \exp(-Nf(H, V) + O(1)) \tag{58}$$

The function f(H, V) as we will see below it is the free energy of the system. It is computed in the next section.

The transfer-matrix in this limit has the asymptotic

$$t(u) = \exp(-Nf(H, V))\hat{t}(u)$$

where the operator $\hat{t}(u)$ acts in the space H_{∞} and its eigenvalues are determined by positions of "particles" and "holes", similarly to the structure of excitations in the large N limit in spin chains.

7.3 Modularity

7.3.1

It is easy to compute now the asymptotic of the partition function in the thermodynamical limit. As $M \to \infty$ the leading term in the formula (57) is given by the largest eigenvalue:

$$Z_{N,M} = \Lambda_0^{(N)M} (1 + O(e^{-\alpha M}))$$

for some positive α .

Taking the limit $N \to \infty$ and taking into account the asymptotic of the largest eigenvalue (58) we identify the function f(H, V) in (58) with the free energy:

$$Z_{N,M} = e^{NMf(H,V)(1+o(1))}$$

7.3.2

Notice now that we could have changed the role of N and M by first taking the limit $N \to \infty$ and then $M \to \infty$.

In this case we would have to compute first the asymptotic of

$$Z_{N,M} = tr(t(u)^M)$$

as $N \to \infty$ and then take the limit $M \to \infty$.

The large N limit of the trace can be computed by using the finite temperature technique developed by Yang and Yang in [39]. It was done by de Vega and Destry [10]. The leading term of the asymptotic can be expressed in terms of the solution to a non-linear integral equation.

This gives an alternative description for the largest eigenvalue. Similar description exists for all eigenvalues. In other integrable quantum field theories it was done by Al. Zamolodchikov [40].

8 The 6-vertex model at the free fermionic point

When $\Delta=0$ the partition function of the 6-vertex model can be expressed in terms of the dimer model on a decorated square lattice. Because the dimer model can be regarded as a theory of free fermions, the 6-vertex model is said to be free fermionic when $\Delta=0$.

At this point the raw-to-raw transfer-matrix on N-sites for a torus can be written in terms of the Clifforrd algebra of \mathbb{C}^N . The Jordan-Wiegner transform maps local spin operators to the elements of the Clifford algebra.

In Bethe equations (37) the variables v_i disappear in the r.h.d which becomes simply $(-1)^{n-1}e^{-2NH}$. After change of variables these equations can be interpreted as the periodic boundary condition for a fermionic wave function.

8.1 Homogeneous case

8.1.1

At the free fermionic point $\Delta = 0$, i.e. $\gamma = \frac{\pi}{2}$ and the weights of the 6-vertex model are parameterized as:

$$a = \sin(\frac{\pi}{2} - u) = \cos(u), \quad b = \sin(u), \quad c = 1$$

Without loosing generality we may assume that $0 < u < \frac{\pi}{4}$.

The eigenvalues of the row-to-row transfer-matrix are given by the Bethe ansatz formulae:

$$\Lambda(u) = ((\cos(u)^N (-1)^n e^{NH} + (\sin(u))^N e^{-NH}) e^{NV} \prod_{i=1}^n (\cot(u - v_i) e^{-2V})$$
 (59)

Here $0 \le n \le N$, and v_i are distinct solutions to the Bethe equations:

$$\cot(v)^N = (-1)^{n-1}e^{-2NH}$$

or:

$$\cot(v) = \omega e^{-2H}$$

where $\omega^{N} = (-1)^{n-1}$.

Using the identity:

$$\cot(u - v) = \frac{\cot u \cot v + 1}{\cot v - \cot u} = \cot u - \frac{1 - \cot^2 u}{\omega e^{-2H} - \cot u}$$

we can write the eigenvalues as:

$$\Lambda(u) = ((\cos(u)^N (-1)^n e^{NH} + (\sin(u))^N e^{-NH}) e^{(N-2n)V}) \prod_{i=1}^n (\cot u - \frac{1 - \cot^2 u}{\omega_i e^{-2H} - \cot u})$$
(60)

8.1.2

To find the maximal eigenvalue in the limit $N \to \infty$ we should analyze factors in the formula (59).

1. If

$$\max_{|\omega|=1} \cot(u-v) < e^{2V}$$

where $\cot(v) = \omega e^{-2H}$, all factor are less then one and the maximal eigenvalue

$$\Lambda_{ord}(u) = (\cos(u)^N e^{NH} + (\sin(u))^N e^{-NH})e^{NV}$$

is achieved when n = 0.

As $N \to \infty$ the first term dominates when $\cot(u) < e^{2H}$. In this case the Gibbs state describing the 6-vertex model in the thermodynamical limit is the ordered state A_1 from Fig. 11 When $\cot(u) > e^{2H}$, the second term dominates. In this case the Gibbs state the ordered state B_2 shown on Fig. 11.

2. If $\min_{|\omega|=1} \cot(u-v) > e^{2V}$ all factors $\cot(u-v_j)e^{2V}$ are greater then

2. If $\min_{|\omega|=1} \cot(u-v) > e^{2V}$ all factors $\cot(u-v_j)e^{2V}$ are greater then one by absolute value. In this case the maximal eigenvalue is achieved when n=N. The corresponding ground state is ordered and in A_2 from Fig. 11 when $\cot u > e^{-2H}$ and is B_1 when $\cot(u) < e^{-2H}$

3. If

$$\max_{|\omega|=1} \cot(u-v) < e^{2V}$$

then there exists $\omega_0 = e^{iK}$ such that

$$|\cot(u-b)| = e^{2V}$$

where $\cot(b) = e^{\pm iK - 2H}$. It is easy to find K:

$$\cos(K) = \frac{(Ue^{2H} + U^{-1}e^{-2H})e^{4V} - (Ue^{-2H} + U^{-1}e^{2H})}{2(e^{4V} + 1)}$$

In this case

$$|\cot(u-v)| > e^{2V}$$

when $\cot(v) = e^{i\alpha}e^{-2H}$ with $-K < \alpha < K$ and

$$|\cot(u-v)| < e^{2V}$$

when $-\pi \leq \alpha < -K$ or $K < \alpha \leq \pi$.

The maximal eigenvalue is this case corresponds to maximal n such that $\frac{\pi(n-1)}{N} < K$ and $\omega_j = \exp(i\frac{\pi(n+1-2j)}{N}), j=1,\ldots,n$ and is given by (59). As $N \to \infty$ the asymptotic of the largest eigenvalue is given by the integral:

$$\log(\Lambda_{disord}(u)) = N(\log(\cos(u)e^H) + \frac{1}{2\pi i} \int_{-K}^{K} \log\left(\frac{\cot(u)\omega e^{-2H} + 1}{\omega e^{-2H} - \cot(u)}\right) \frac{d\omega}{\omega}) + O(1)$$

The 6-vertex in this regime is in the disordered phase.

Disordered and ordered phases are separated by the curve

$$\max_{|\omega|=1} |\cot(u-v)| = e^{-2V}, \quad \min_{|\omega|=1} |\cot(u-v)| = e^{-2V},$$

or, more explicitly

$$\left|\frac{Ue^{-2H} \mp 1}{U \pm e^{-2H}}\right| = e^{-2V}$$

This curve is shown on Fig. 8

8.2 Horizontally inhomogeneous case

The partition function for the 6-vertex model at the free fermionic point with inhomogeneous rows is

$$Z_{N,M}(u,a) = \sum_{n=0}^{N} \sum_{\omega_1,\dots,\omega_n} \Lambda(u+a|\omega)^M \Lambda(u-a|\omega)^M$$

where $\omega_i \neq \omega_j$ are solutions to

$$\omega^N = (-1)^{n-1}$$

and $\Lambda(u|\omega)$ is given by (60).

The boundary between ordered and disordered phases is given by equations

$$\max_{|\omega|=1} |\cot(u+a-v)\cot(u-a-v)| = e^{4V}, \quad \min_{|\omega|=1} |\cot(u+a-v)\cot(u-a-v)| = e^{4V}$$

or,

$$\left| \frac{U_{+}e^{-2H} \pm 1}{U_{+} \mp e^{-2H}} \right| \left| \frac{U_{-}e^{-2H} \pm 1}{U_{-} \mp e^{-2H}} \right| = e^{4V}$$
 (61)

This curve is shown on Fig. 9.

The ordered phases $A1B_2$ and A_2B_1 are shown on Fig. 10.

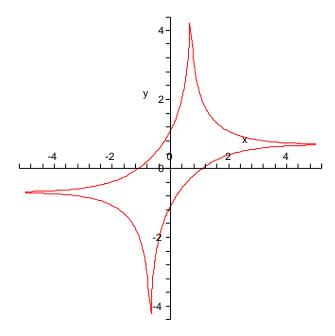


Figure 8: The boundary ordered and disordered regions in the (H, V)-plane for the homogeneous 6-vertex model with $\Delta = 0$ and $U = \cot(u) = 2$

The free energy per site in the disordered region is given by

$$f(H,V) = \log(\cos(u+a)\cos(u-a) + \frac{1}{2\pi i} \int_{-K_1}^{K_1} \log\left(\frac{\cot(u+a)\omega e^{-2H} + 1}{\omega e^{-2H} - \cot(u+a)} \frac{\cot(u-a)\omega e^{-2H} + 1}{\omega e^{-2H} - \cot(u-a)}\right) \frac{d\omega}{\omega}) + \frac{1}{2\pi i} \int_{-K_2}^{K_2} \log\left(\frac{\cot(u+a)\omega e^{-2H} + 1}{\omega e^{-2H} - \cot(u+a)} \frac{\cot(u-a)\omega e^{-2H} + 1}{\omega e^{-2H} - \cot(u-a)}\right) \frac{d\omega}{\omega})$$
(62)

where $K_{1,2}$ are defined by equations

$$|\cot(u+a-b)\cot(u-a-b)| = e^{2V}$$

with $\cot(b) = e^{\pm iK}e^{-2H}$.

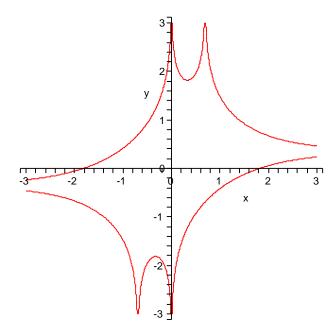


Figure 9: The boundary between ordered and disordered regions in the (H, V)plane for the inhomogeneous 6-vertex model with $\Delta = 0$ and $U = \cot(u) =$ $3, T = \cot(a) = 1$

8.3 Vertically non-homogeneous case

8.3.1

Assume the weights are homogeneous in the vertical direction and alternate in the horizontal direction with parameters alternating as ..., $u+a, u-a, u+a, u-a, \ldots$. Positivity of weights in the region $0 \le u \le \frac{\pi}{4}$ requires $0 \le a \le u$. The eigenvalues of the transfer-matrix are given by the Bethe ansatz:

$$\Lambda(u) = ((\cos(u+a)\cos(u-a))^N (-1)^n e^{NH} + (\sin(u+a)\sin(u-a))^N e^{-NH})$$

$$e^{(N-2n)V} \prod_{i=1}^n \cot(u-v_i) \quad (63)$$

where v_i are distinct solutions to

$$(\cot(v-a)\cot(v+a))^N = (-1)^{n-1}e^{-2NH}$$

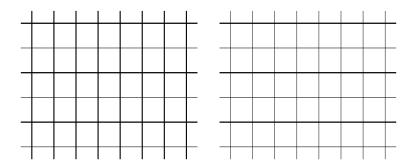


Figure 10: Horizontally inhomogeneous ordered phases A_1B_2 and A_2B_1 respectively

The left side is the N-th power of

$$\frac{\cot(v)\cot(a)+1}{\cot(a)-\cot(v)}\frac{-\cot(v)\cot(a)+1}{-\cot(a)-\cot(v)}=\frac{\cot(v)^2\cot(a)^2-1}{\cot(a)^2-\cot(v)^2}$$

From here it is easy to find the parametrization of solutions by roots of unity:

$$\cot(v)^{2} = \frac{\omega \cot(a)^{2} e^{-2H} + 1}{\cot(a)^{2} + \omega e^{-2H}}$$
(64)

where

$$\omega^N = (-1)^{n-1}$$

8.3.2 Largest eigenvalue

The analysis of the largest eigenvalue of the transfer-matrix in the limit $N\to\infty$ is similar to the previous cases. When

$$\max_{|\omega|=1} |\cot(u-v)| \ge e^{2V} \tag{65}$$

where v and ω are related as in (64) the absolute value of all factors $\cot(u-v)|e^{-2V}$ is greater then one by the absolute value and the largest eigenvalue correspond to n=0. The rest of the analysis is similar.

Let us notations:

$$T = \cot(a), \quad x = e^{-H}, \quad U = \cot(u), \quad s = \cot(v)$$

Positivity of weights imply

$$T \ge U > 0$$

Proposition 1. The curve separating ordered phases from the disordered phase is

$$X = \left| \frac{YU_{+} - 1}{Y + U_{+}} \right| \left| \frac{YU_{-} - 1}{Y + U_{-}} \right|$$

Proof. In the notations from above:

$$|\cot(u-v)|^2 = \left|\frac{\cot(u)\cot(v)+1}{\cot(v)-\cot(u)}\right|^2 = \frac{Us+1}{s-U}\frac{U\bar{s}+1}{\bar{s}-U} = \frac{U^2|s|^2+2URe(s)+1}{U^2-2URe(s)+|s|^2}$$

The equation of the boundary of the disordered region is

$$\max_{|\omega|=1} |\cot(u-v)| = e^{2V}$$

The equation defining v in terms of roots of unity ω can be solved explicitly for $s=\cot v$:

$$s^2 = \frac{T^2 x^2 \omega + 1}{T^2 + \omega x^2}$$

Denote $\omega = e^{i\alpha}$, then

$$s^{2} = \frac{(T^{2}x^{2}\cos(\alpha) + 1) + iT^{2}x^{2}\sin(\alpha)}{(T^{2} + x^{2}\cos(\alpha)) + ix^{2}\sin(\alpha)}$$

$$Re(s^{2}) = \frac{(T^{2}x^{2}\cos(\alpha) + 1)(T^{2} + x^{2}\cos(\alpha)) + T^{2}x^{2}\sin(\alpha)x^{2}\sin(\alpha)}{(T^{2} + x^{2}\cos(\alpha))^{2} + x^{4}\sin(\alpha)^{2}}$$

$$|s|^{4} = \frac{T^{4}x^{4} + 2T^{2}x^{2}\cos(\alpha) + 1}{T^{4} + 2T^{2}x^{2}\cos(\alpha) + x^{4}}$$

Now, a simple algebra:

$$Re(s) = \sqrt{\frac{Re(s^2) + |s|^2}{2}}$$

As we vary ω along the unit circle, the function $\cot(u-v)$ has maximum at $\omega=1$.

Taking this into account the equation for the boundary curve becomes

$$\left| \frac{U\sqrt{1+x^2T^2} \pm \sqrt{T^2+x^2}}{U\sqrt{T^2+x^2} \pm \sqrt{1+x^2T^2}} \right| = e^{2V}$$

Solving this equation for $X = x^2 = e^{-2H}$ in terms of $Y = e^{2V}$ we obtain

$$X = \left| \frac{YU_{+} - 1}{Y + U_{+}} \right| \left| \frac{YU_{-} - 1}{Y + U_{-}} \right|$$

which is, after changing coordinates to X^{-1}, Y^{-1} is the same curve as (61). This is one of the implications of the modular symmetry.

By modularity, i.e. by "rotating" the lattice with periodic boundary conditions by 90 degrees, all characteristics of the model with vertical inhomogeneities can be identifies with the corresponding characteristics of the model with horizontal inhomogeneities.

9 The free energy of the 6-vertex model

The computation of the free energy for the 6-vertex model by taking the large N, M limit of the partition function on a torus was outlines in section 7.1. In this section we will describe the free energy as a function of electric fields (H, V) and its basic properties.

9.1 The phase diagram for $\Delta > 1$

9.1.1

The weights a, b, and c in this region satisfy one of the two inequalities, either a > b + c or b > a + c.

If a > b + c, the Boltzmann weights a, b, and c can be parameterized as

$$a = r \sinh(\lambda + \eta), b = r \sinh(\lambda), c = r \sinh(\eta)$$
(66)

with $\lambda, \eta > 0$.

If a + c < b, the Boltzmann weights can be parameterized as

$$a = r \sinh(\lambda - \eta), b = r \sinh(\lambda), c = r \sinh(\eta)$$
(67)

with $0 < \eta < \lambda$.

For both of these parametrization of weights $\Delta = \cosh(\eta)$.

The phase diagram of the model for a > b + c (and, therefore, a > b) is shown on Fig. 12 and for b > a + c (and, therefore, a < b) on Fig. 13.

9.1.2

When magnetic fields (H, V) are in one of the regions A_i, B_i of the phase diagram, the system in the thermodynamic limit is described by the translationally invariant Gibbs measure supported on the corresponding frozen (ordered) configurations. There are four frozen configurations A_1, A_2, B_1 , and B_2 , shown on Fig. 11. For a finite but large grid the probability of any other state is of the order at most $\exp(-\alpha N)$ for some positive α .

Local correlation functions in a frozen state are products of expectation values of characteristic functions of edges.

$$\lim_{N \to \infty} \langle \sigma_{e_1} \dots \sigma_{e_n} \rangle_N = \sigma_{e_1}(S) \dots \sigma_{e_n}(S)$$

where S is the one of the ferromagnetic states A_i, B_i .

9.1.3

The boundary between ordered phases in the (H, V)-plane and disordered phases, as in the free fermionic case, is determined by the next to the largest eigenvalue of the row-to-row transfer matrix.

Without going into the details of the computations as we did in the free fermionic case we will just give present answers.

• a > b + c, see Fig. 12,

$$\begin{split} A_{1}\text{-region:} & V+H \geq 0, & \cosh(2H) \leq \Delta, \\ & (e^{2H}-b/a)(e^{2V}-b/a) \geq (c/a)^{2}, & e^{2H}>b/a, & \cosh(2H)>\Delta, \\ A_{2}\text{-region:} & V+H \leq 0, & \cosh(2H) \leq \Delta, \\ & (e^{-2H}-b/a)(e^{-2V}-b/a) \geq (c/a)^{2}, & e^{-2H}>b/a, & \cosh(2H)>\Delta, \\ B_{1}\text{-region:} & (e^{2H}-a/b)(e^{-2V}-a/b) \geq (c/b)^{2}, & e^{2H}>a/b, \\ B_{2}\text{-region:} & (e^{-2H}-a/b)(e^{2V}-a/b) \geq (c/b)^{2}, & e^{-2H}>a/b. \end{split}$$

• b > a + c, see Fig. 13,

$$\begin{split} &A_1\text{-region:} \qquad (e^{2H}-b/a)(e^{2V}-b/a) \geq (c/a)^2, \qquad e^{2H} > b/a; \\ &A_2\text{-region:} \qquad (e^{-2H}-b/a)(e^{-2V}-b/a) \geq (c/a)^2, \qquad e^{-2H} > b/a; \\ &B_1\text{-region:} \qquad V-H \geq 0, \qquad \cosh(2H) \leq \Delta, \\ &\qquad (e^{2H}-a/b)(e^{-2V}-a/b) \geq (c/b)^2, \qquad e^{2H} > a/b, \qquad \cosh(2H) > \Delta, \\ &B_2\text{-region:} \qquad V-H \leq 0, \qquad \cosh(2H) \leq \Delta, \\ &\qquad (e^{-2H}-a/b)(e^{2V}-a/b) \geq (c/b)^2, \qquad e^{-2H} > a/b, \qquad \cosh(2H) > \Delta. \end{split}$$

The free energy is a linear function in H and V in the four frozen regions:

$$f = -\ln a - H - V$$
 in A_1 ,
 $f = -\ln b + H - V$ in B_2 ,
 $f = -\ln a + H + V$ in A_2 ,
 $f = -\ln b - H + V$ in B_1 .

The regions D_1 and D_2 are disordered phases. If (H, V) is in one of these regions, local correlation functions are determined by the unique Gibbs measure with the polarization given by the gradient of the free energy. In this phase the system is disordered, which means that local correlation functions decay as a power of the distance $d(e_i, e_j)$ between e_i and e_j when $d(e_i, e_j) \to \infty$.

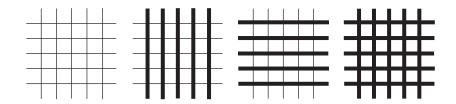


Figure 11: Four frozen configurations of the ferromagnetic phase

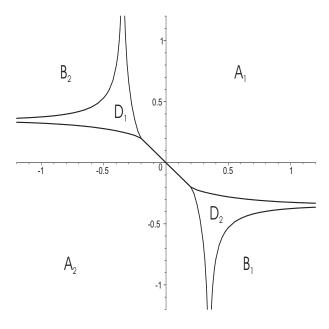


Figure 12: The phase diagram in the (H, V)-plane for a = 2, b = 1, and c = 0.8

In the regions D_1 and D_2 the free energy is given by [37]:

$$f(H,V) = \min(\min_{\alpha} \left(E_1 - H - (1 - 2\alpha)V - \frac{1}{2\pi i} \int_C \ln(\frac{b}{a} - \frac{c^2}{ab - a^2 z})\rho(z)dz \right),$$

$$\min_{\alpha} \left(E_2 + H - (1 - 2\alpha)V - \frac{1}{2\pi i} \int_C \ln(\frac{a^2 - c^2}{ab} + \frac{c^2}{ab - a^2 z})\rho(z)dz \right), \quad (69)$$

where $\rho(z)$ can be found from the integral equation

$$\rho(z) = \frac{1}{z} + \frac{1}{2\pi i} \int_C \frac{\rho(w)}{z - z_2(w)} dw - \frac{1}{2\pi i} \int_C \frac{\rho(w)}{z - z_1(w)} dw, \tag{70}$$

in which

$$z_1(w) = \frac{1}{2\Delta - w}, \qquad z_2(w) = -\frac{1}{w} + 2\Delta.$$

 $\rho(z)$ satisfies the following normalization condition:

$$\alpha = \frac{1}{2\pi i} \int_C \rho(z) dz.$$

The contour of integration C (in the complex z-plane) is symmetric with respect to the conjugation $z \to \bar{z}$, is dependent on H and is defined by the condition that the form $\rho(z)dz$ has purely imaginary values on the vectors tangent to C:

$$\operatorname{Re}(\rho(z)dz)\Big|_{z\in C} = 0.$$

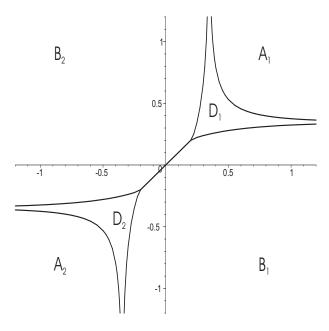


Figure 13: The phase diagram in the (H, V)-plane for a = 1, b = 2, and c = 0.8

The formula (69) for the free energy follows from the Bethe Ansatz diagonalization of the row-to-row transfer-matrix. It relies on a number of conjectures that are supported by numerical and analytical evidence and in physics are taken for granted. However, there is no rigorous proof.

There are two points where three phases coexist (two frozen and one disordered phase). These points are called *tricritical*. The angle θ between the boundaries of D_1 (or D_2) at a tricritical point is given by

$$\cos(\theta) = \frac{c^2}{c^2 + 2\min(a, b)^2(\Delta^2 - 1)}.$$

The existence of such points makes the 6-vertex model (and its degeneration known as the 5-vertex model [15]) remarkably different from dimer models [20] where generic singularities in the phase diagram are cusps. Physically, the existence of singular points where two curves meet at the finite angle manifests the presence of interaction in the 6-vertex model.

Notice that when $\Delta=1$ the phase diagram of the model has a cusp at the point H=V=0. This is the transitional point between the region $\Delta>1$ and the region $|\Delta|<1$ which is described below.

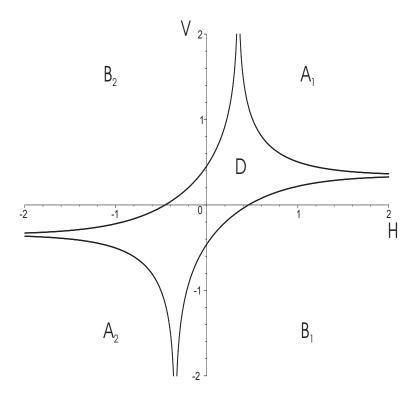


Figure 14: The phase diagram in the (H, V)-plane for a = 1, b = 2, and c = 2

9.2 The phase diagram $|\Delta| < 1$

In this case, the Boltzmann weights have a convenient parametrization by trigonometric functions. When $1\geq \Delta \geq 1$

$$a = r \sin(\lambda - \gamma), b = r \sin(\lambda), c = r \sin(\gamma),$$

where $0 \le \gamma \le \pi/2, \, \gamma \le \lambda \le \pi$, and $\Delta = \cos \gamma$. When $0 \ge \Delta \ge -1$

$$a = r \sin(\gamma - \lambda), b = r \sin(\lambda), c = r \sin(\gamma),$$

where $0 \le \gamma \le \pi/2$, $\pi - \gamma \le \lambda \le \pi$, and $\Delta = -\cos \gamma$.

The phase diagram of the 6-vertex model with $|\Delta| < 1$ is shown on Fig. 14. The phases A_i, B_i are frozen and identical to the frozen phases for $\Delta > 1$. The phase D is disordered. For magnetic fields (H, V) the Gibbs measure is translationally invariant with the slope $(h, v) = (\frac{\partial f(H, V)}{\partial H}, \frac{\partial f(H, V)}{\partial V})$.

The frozen phases can be described by the following inequalities:

$$A_{1}\text{-region:} \qquad (e^{2H} - b/a)(e^{2V} - b/a) \ge (c/a)^{2}, \qquad e^{2H} > b/a,$$

$$A_{2}\text{-region:} \qquad (e^{-2H} - b/a)(e^{-2V} - b/a) \ge (c/a)^{2}, \qquad e^{-2H} > b/a,$$

$$B_{1}\text{-region:} \qquad (e^{2H} - a/b)(e^{-2V} - a/b) \ge (c/b)^{2}, \qquad e^{2H} > a/b, \quad (71)$$

$$B_{2}\text{-region:} \qquad (e^{-2H} - a/b)(e^{2V} - a/b) \ge (c/b)^{2}, \qquad e^{-2H} > a/b.$$

The free energy function in the frozen regions is still given by the formulae (69). The first derivatives of the free energy are continuous at the boundary of frozen phases, The second derivative is continuous in the tangent direction at the boundary of frozen phases and is singular in the normal direction.

It is smooth in the disordered region where it is given by (69) which, as in case $\Delta > 1$ involves a solution to the integral equation (70). The contour of integration in (70) is closed for zero magnetic fields and, therefore, the equation (70) can be solved explicitly by the Fourier transformation [3].

The 6-vertex Gibbs measure with zero magnetic fields converges in the thermodynamic limit to the superposition of translationally invariant Gibbs measures with the slope (1/2, 1/2). There are two such measures. They correspond to the double degeneracy of the largest eigenvalue of the row-to-row transfermatrix [3].

There is a very interesting relationship between the 6-vertex model in zero magnetic fields and the highest weight representation theory of the corresponding quantum affine algebra. The double degeneracy of the Gibbs measure with the slope (1/2, 1/2) corresponds to the fact that there are two integrable irreducible representations of $\widehat{sl_2}$ at level one. Correlation functions in this case can be computed using q-vertex operators [17]. For latest developments see [7].

9.3 The phase diagram $\Delta < -1$

9.3.1 The phase diagram

The Boltzmann weights for these values of Δ can be conveniently parameterized as

$$a = r \sinh(\eta - \lambda), b = r \sinh(\lambda), c = r \sinh(\eta), \tag{72}$$

where $0 < \lambda < \eta$ and $\Delta = -\cosh \eta$.

The Gibbs measure in thermodynamic limit depends on the value of magnetic fields. The phase diagram in this case is shown on Fig. 15 for b/a > 1. In the parameterization (72) this correspond to $0 < \lambda < \eta/2$. When $\eta/2 < \lambda < \eta$ the 4-tentacled "amoeba" is tilted in the opposite direction as on Fig. 12.

When (H, V) is in one of the A_i, B_i regions in the phase diagram the Gibbs measure is supported on the corresponding frozen configuration, see Fig. 11.

The boundary between ordered phases A_i , B_i and the disordered phase D is given by inequalities (71). The free energy in these regions is linear in electric fields and is given by (69).

If (H, V) is in the region D, the Gibbs measure is the translationally invariant measure with the polarization (h, v) determined by (54). The free energy in this

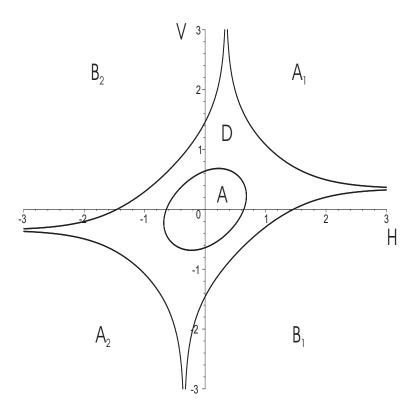


Figure 15: The phase diagram in the (H, V)-plane for a = 1, b = 2, and c = 6

case is determined by the solution to the linear integral equation (70) and is given by the formula (69).

If (H, V) is in the region A, the Gibbs measure is the superposition of two Gibbs measures with the polyarization (1/2, 1/2). In the limit $\Delta \to -\infty$ these two measures degenerate to two measures supported on configurations C_1, C_2 , respectively, shown on Fig. 16. For a finite Δ the support of these measures consists of configurations which differ from C_1 and C_2 in finitely many places on the lattice.

Remark 4. Any two configurations lying in the support of each of these Gibbs measures can be obtained from C_1 or C_2 via flipping the path at a vertex "up" or "down" as it is shown on Fig. 17 finitely many times. It is also clear that it takes infinitely many flips to go from C_1 to C_2 .

9.3.2 The antiferromagnetic region

The 6-vertex model in the phase A is disordered and is also noncritical. Here the non-criticality means that the local correlation function $\langle \sigma_{e_i} \sigma_{e_j} \rangle$ decays as

 $\exp(-\alpha d(e_i, e_j))$ with some positive α as the distance $d(e_i, e_j)$ between e_i and e_j increases to infinity.

The free energy in the A-region can be explicitly computed by solving the equation (70). In this case the largest eigenvalue will correspond to n=N/2, the contour of integration in (70) is closed, and the equation can be solved by the Fourier transform. ².

The boundary between the antiferromagnetic region A and the disordered region D can be derived similarly to the boundaries of the ferromagnetic regions A_i and B_i by analyzing next to the largest eigenvalue of the row-to-row transfermatrix. This computation was done in [37], [24]. The result is a simple closed curve, which can be described parameterically as

$$H(s) = \Xi(s),$$
 $V(s) = \Xi(\eta - \theta_0 + s),$

where

$$\Xi(\varphi) = \cosh^{-1}\left(\frac{1}{\operatorname{dn}\left(\frac{K}{\pi}\varphi|1-\nu\right)}\right),$$
$$|s| \le 2\eta,$$

and

$$e^{\theta_0} = \frac{1 + \max(b/a, a/b)e^{\eta}}{\max(b/a, a/b) + e^{\eta}}.$$

The parameter ν is defined by the equation $\eta K(\nu) = \pi K'(\nu)$, where

$$K(\nu) = \int_0^{\pi/2} (1 - \nu \sin^2(\theta))^{-1/2} d\theta \qquad K'(\nu) = \int_0^{\pi/2} (1 - (1 - \nu) \sin^2(\theta))^{-1/2} d\theta.$$

The curve is invariant with respect to the reflections $(H, V) \to (-H, -V)$ and $(H, V) \to (V, H)$ since the function Ξ satisfies the identities

$$\Xi(\varphi) = -\Xi(-\varphi), \qquad \Xi(\eta - \varphi) = \Xi(\eta + \varphi).$$

²Strictly speaking this is a conjecture supported by the numerical evidence

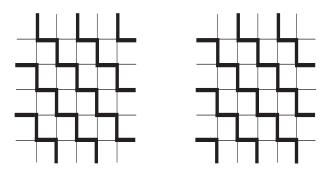


Figure 16: The configurations C_1 and C_2 .

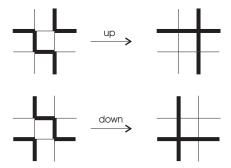


Figure 17: The elementary up and down fluctuations in the antiferromagnetic phase.

This function is also 4η -periodic: $\Xi(4\eta + \varphi) = \Xi(\varphi)$.

As it was shown in [29] this curve is algebraic in e^H and e^V and can be written as

$$\left((1 - \nu \cosh^2 V_0) \cosh^2 H + \sinh^2 V_0 - (1 - \nu) \cosh V_0 \cosh H \cosh V \right)^2 =$$

$$\left(1 - \nu \cosh^2 V_0 \right) \sinh^2 V_0 \cosh^2 V \sinh^2 H (1 - \nu \cosh^2 H), \tag{73}$$

where V_0 is the positive value of V on the curve when H=0. Notice that ν depends on the Boltzmann weights a,b,c only through η .

10 Some asymptotics of the free energy

10.1 The scaling near the boundary of the *D*-region

Assume that $\vec{H}_0 = (H_0, V_0)$ is a regular point at the boundary between the disordered region and and the A_1 -region, see Fig.14. Recall that this boundary is the curve defined by the equation

$$q(H, V) = 0$$

where

$$g(H,V) = \ln(b/a + \frac{c^2/a^2}{e^{2H} - b/a}) - 2V.$$
 (74)

Denote the normal vector to the boundary of the *D*-region at \vec{H}_0 by \vec{n} and the tangent vector pointing inside of the region *D* by $\vec{\tau}$.

We will study the asymptotic of the free energy along the curves $\vec{H}(r, s, t) = \vec{H_0} + r^2 s \vec{n} + r t \vec{\tau}$, as $r \to 0$. It is clear that $\vec{H}(r, s, t)$ is in the *D*-region if $s \ge 0$.

Theorem 2. Let $\vec{H}(r, s, t)$ be defined as above. The asymptotic of the free energy of the 6-vertex model in the limit $r \to 0$ is given by

$$f(\vec{H}(r,s,t)) = f_{lin}(\vec{H}(r,s,t)) + \eta(s,t)r^3 + O(r^5), \tag{75}$$

where $f_{lin}(H, V) = -\ln(a) - H - V$ and

$$\eta(s,t) = -\kappa \left(\theta s + t^2\right)^{3/2}.\tag{76}$$

Here the constants κ and θ depend on the Boltzmann weights of the model and on (H_0, V_0) and are given by

$$\kappa = \frac{16}{3\pi} \, \partial_H^2 g(H_0, V_0)$$

and

$$\theta = \frac{4 + (\partial_H g(H_0, V_0))^2}{2\partial_H^2 g(H_0, V_0)},$$

where g(H, V) is defined in (74).

Moreover, $\partial_H^2 g(H_0, V_0) > 0$ and, therefore, $\theta > 0$.

We refer the reader to [29] for the details. This behavior is universal in a sense that the exponent 3/2 is the same for all points at the boundary.

10.2 The scaling in the tentacle

Here, to be specific we assume that a > b. The theorem below describes the asymptotic of the free energy function when $H \to +\infty$ and

$$\frac{1}{2}\ln(b/a) - \frac{c^2}{2ab}e^{-2H} \le V \le \frac{1}{2}\ln(b/a) + \frac{c^2}{2ab}e^{-2H}, \qquad H \longrightarrow \infty.$$
 (77)

These values of (H, V) describe points inside the right "tentacle" on the Fig. 12.

Let us parameterize these values of V as

$$V = \frac{1}{2}\ln(b/a) + \beta \frac{c^2}{2ab}e^{-2H},$$

where $\beta \in [-1, 1]$.

Theorem 3. When $H \to \infty$ and $\beta \in [-1,1]$ the asymptotic of the free energy is given by the following formula:

$$f(H,V) = -\frac{1}{2}\ln(ab) - H - \frac{c^2}{2ab}e^{-2H}\left(\beta + \frac{2}{\pi}\sqrt{1-\beta^2} - \frac{2}{\pi}\beta\arccos(\beta)\right) + O(e^{-4H}),$$

The proof is given in [29].

10.3 The 5-vertex limit

The 5-vertex model can be obtained as the limit of the 6-vertex model when $\Delta \to \infty$. Magnetic fields in this limit behave as follows:

• a > b + c. In the parametrization (66) after changing variables $H = \frac{\eta}{2} + l$, and $V = -\frac{\eta}{2} + m$ take the limit $\eta \to \infty$ keeping λ fixed. The weights will converge (up to a common factor) to:

$$a_1:a_2:b_1:b_2:c_1:c_2\to e^{\lambda+l+m}:e^{\lambda-l-m}:(e^{\lambda}-e^{-\lambda})e^{l-m}:0:1:1$$

• a+c < b. In the parametrization (67) after changing variables $H = \frac{\eta}{2} + l$, and $V = \frac{\eta}{2} + m$ take the limit $\eta \to \infty$ keeping $\xi = \lambda - \eta$ fixed. The weights will converge (up to a common factor) to:

$$a_1: a_2: b_1: b_2: c_1: c_2 \to (e^{\xi} - e^{-\xi})e^{l+m}: 0: e^{\xi+l-m}: e^{\xi-l+m}: 1: 1$$

The two limits are related by inverting horizontal arrows. From now on we will focus on the 5-vertex model obtained by the limit from the 6-vertex one when a > b + c.

The phase diagram of the 5-vertex model is easier then the one for the 6-vertex model but still sufficiently interesting. Perhaps the most interesting feature is that the existence of the tricritical point in the phase diagram.

We will use the parameter

$$\gamma = e^{-2\lambda}$$

Notice that $\gamma < 1$.

The frozen regions on the phase diagram of the 5-vertex model, denoted on Fig. 18 as A_1 , A_2 , and B_1 , can be described by the following inequalities:

$$A_{1}\text{-region:} \qquad m \geq -l, \qquad l \leq 0, \\ e^{2m} \geq 1 - \gamma(1 - e^{-2l}), \qquad l > 1; \\ A_{2}\text{-region:} \qquad m \leq -l, \qquad l \leq 0, \\ e^{2m} \leq 1 - \frac{1}{\gamma}(1 - e^{-2l}), \qquad l > 1; \\ B_{1}\text{-region:} \qquad (e^{2l} - \frac{1}{1 - \gamma})(e^{-2m} - \frac{1}{1 - \gamma}) \geq \frac{\gamma}{(1 - \gamma)^{2}}, \qquad e^{2l} > \frac{1}{1 - \gamma};$$

As it follows from results [15] the limit from the 6-vertex model to the 5-vertex model commutes with the thermodynamical limit and for the free energy of the 5-vertex model we can use the formula

$$f_5(l,m) = \lim_{\eta \to +\infty} (f(\eta/2 + l, -\eta/2 + m) - f(\eta/2, -\eta/2)), \tag{79}$$

where f(H, V) is the free energy of the 6-vertex model.

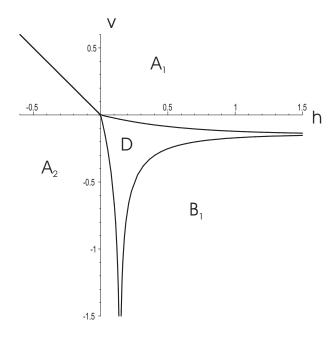


Figure 18: The phase diagram of the 5-vertex model with $\gamma=1/4$ ($\beta=e^{-2h}$).

10.4 The asymptotic of the free energy near the tricritical point in the 5-vertex model

The disordered region D near the tricritical point forms a corner

$$-\frac{1}{\gamma}l + O(l^2) \le m \le -\gamma l + O(l^2), \qquad h \to 0 + .$$

The angle θ between the boundaries of the disordered region at this point is given by

$$\cos(\theta) = \frac{2\gamma}{1 + \gamma^2}.$$

One can argue that the finiteness of the angle θ manifests the presence of interaction in the model. In comparison, translation invariant dimer models most likely can only have cusps as such singularities.

Let
$$\gamma \le k \le \frac{1}{\gamma}$$
 and

$$m = -kl$$
,

As it was shown in [6] for m=-l and in [29] for m=-kl with $\gamma \leq k \leq \frac{1}{\gamma}$ the asymptotic of the free energy as $l \to +0$ is given by

$$f(l, -kl) = c_1(k, \gamma)l + c_2(k, \gamma)l^{5/3} + O(l^{7/3}).$$
(80)

where

$$c_1(k,\gamma) = \frac{1}{1-\gamma} \left(-(1+k)(1+\gamma) + 4\sqrt{k\gamma} \right), \tag{81}$$

and

$$c_2(k,\gamma) = (6\pi)^{2/3} \frac{2\gamma^{5/6}(1-\gamma)k^{3/2}(\sqrt{k}-1/\sqrt{\gamma})^{4/3}}{5(\sqrt{k}-\sqrt{\gamma})^{4/3}}.$$
 (82)

The scaling along any ray inside the corner near the tricritical point in the 6-vertex model differ from this only by in coefficients. The exponent $h^{5/3}$ is the same.

10.5 The limit $\Delta \rightarrow -1^-$

If $\Delta = -1$, the region A consists of one point located at the origin.

It is easy to find the asymptotic of the function $\Xi(\varphi)$ when $\eta \to 0+$, or $\Delta \to -1-$. In this limit $K' \to \pi/2$, $K \to \frac{\pi^2}{2\eta}$. Using the asymptotic $\frac{1}{\operatorname{dn}(u|1-m)} \sim 1 + \frac{1}{2}(1-m)\sin^2(u)$ when $m \to 1-$, and $\cosh^{-1}(x) \sim \pm \sqrt{2(x-1)}$, when $x \to 1+$, we have

$$\theta_0 = \frac{|b - a|\eta}{a + b}.$$

and [24]:

$$\Xi(\varphi) \sim 4e^{-\frac{\pi^2}{2\eta}}\sin(\frac{\pi}{2\eta}\varphi).$$

The gap in the spectrum of elementary excitations vanishes in this limit at the same rate as $\Xi(\varphi)$. At the lattice distances of order $e^{\frac{\pi^2}{2\eta}}$ the theory has a scaling limit and become the relativistic SU(2) chiral Thirring model. Correlation function of vertical and horizontal edges in the 6-vertex model become correlation functions of the currents in the Thirring model.

10.6 The convexity of the free energy

The following identity holds in the region D [4],[26]:

$$f_{H,H}f_{V,V} - f_{H,V}^2 = \left(\frac{2}{\pi g}\right)^2.$$
 (83)

Here $g = \frac{1}{2D_0^2}$. The constant D_0 does not vanish in the D-region including its boundary. It is determined by the solution to the integral equation for the density $\rho(z)$.

Directly from the definition of the free energy we have

$$f_{H,H} = \lim_{N,M\to\infty} \frac{\langle (n(L) - n(R))^2 \rangle}{NM},$$

where n(L) and n(R) are the number of arrows pointing to the left and the number of arrows pointing to the right, respectively.

Therefore, the matrix $\partial_i \partial_j f$ of second derivatives with respect to H and V is positive definite.

As it follows from the asymptotical behavior of the free energy near the boundary of the *D*-phase, despite the fact that the Hessian is nonzero and finite at the boundary of the interface, the second derivative of the free energy in the transversal direction at a generic point of the interface develops a singularity.

11 The Legendre Transform of the Free Energy

The Legendre transform of the free energy

$$\sup_{H,V} \left(xH + yV + f(H,V) \right)$$

as a function of (x, y) is defined for $-1 \le x, y \le 1$.

The variables x and y are known as polarizations and are related to the slope of the Gibbs measure as x = 2h - 1 and y = 2v - 1. We will write the Legendre transform of the free energy as a function of (h, v)

$$\sigma(h,v) = \sup_{H,V} \Big((2h-1)H + (2v-1)V + f(H,V) \Big). \tag{84}$$

 $\sigma(h, v)$ is defined on $0 \le h, v \le 1$.

For the periodic boundary conditions the surface tension function has the following symmetries:

$$\sigma(x, y) = \sigma(y, x) = \sigma(-x, -y) = \sigma(-y, -x).$$

The last two equalities follow from the fact that if all arrows are reversed, σ is the same, but the signs of x and y are changed. It follows that $\sigma_h(h, v) = \sigma_v(v, h)$ and $\sigma_v(h, v) = \sigma_h(v, h)$.

The function f(H, V) is linear in the domains that correspond to conic and corner singularities of σ . Outside of these domains (in the disordered domain D) we have

$$\nabla \sigma \circ \nabla f = \mathrm{id}_D, \ \nabla f \circ \nabla \sigma = \mathrm{id}_{\nabla f(D)}. \tag{85}$$

Here the gradient of a function as a mapping $\mathbb{R}^2 \to \mathbb{R}^2$.

When the 6-vertex model is formulated in terms of the height function, the Legendre transform of the free energy can be regarded as a surface tension. The surface in this terminology is the graph of of the height function.

11.1

Now let us describe some analytical properties of the function $\sigma(h, v)$ is obtained as the Legendre transform of the free energy. The Legendre transform maps the regions where the free energy is linear with the slope $(\pm 1, \pm 1)$ to the corners of the unit square $\mathcal{D} = \{(h, v) | 0 \le h \le 1, 0 \le v \le 1\}$. For example, the region A_1 is mapped to the corner h = 1 and v = 1 and the region B_1 is mapped to the corner h = 1 and v = 0. The Legendre transform maps the tentacles of the

disordered region to the regions adjacent to the boundary of the unit square. For example, the tentacle between A_1 and B_1 frozen regions is mapped into a neighborhood of h = 1 boundary of \mathcal{D} , i.e. $h \to 1$ and 0 < v < 1.

Applying the Legendre transform to asymptotics of the free energy in the tentacle between A_1 and B_1 frozen regions we get

$$H(h,v) = -\frac{1}{2}\ln\left(\frac{\pi ab}{c^2}\frac{1-h}{\sin\pi(1-v)}\right), \qquad V(h,v) = \frac{1}{2}\ln(b/a) + \frac{\pi}{2}(1-h)\cot(\pi(1-v)),$$

and

$$\sigma(h, v) = (1 - h) \ln \left(\frac{\pi a b}{c^2} \frac{1 - h}{\sin(\pi (1 - v))} \right) - (1 - h) + v \ln(b/a) - \ln(b), \quad (86)$$

Here $h \to 1-$ and 0 < v < 1. From (86) we see that $\sigma(1, v) = v \ln(b/a) - \ln(b)$, i.e. σ is linear on the boundary h = 1 of \mathcal{D} . Therefore, its asymptotics near the boundary h = 1 is given by

$$\sigma(h, v) = v \ln(b/a) - \ln(b) + (1 - h) \ln(1 - h) + O(1 - h),$$

as $h \to 1-$ and 0 < v < 1. We note that this expansion is valid when $(1 - h)/\sin(\pi(1 - v)) \ll 1$.

Similarly, considering other tentacles of the region D, we conclude that the surface tension function is linear on the boundary of \mathcal{D} .

11.2

Next let us find the asymptotics of σ at the corners of \mathcal{D} in the case when all points of the interfaces between frozen and disordered regions are regular, i.e. when $\Delta < 1$. We use the asymptotics of the free energy near the interface between A_1 and D regions (75).

First let us fix the point (H_0, V_0) on the interface and the scaling factor r in (75). Then from the Legendre transform we get

$$1 - h = -\frac{3}{4}r \frac{\kappa(\theta s + t^2)^{1/2}}{(\partial_H g)^2 + 4} (\theta \partial_H g + 4rt)$$

and

$$1 - v = -\frac{3}{2} r \frac{\kappa (\theta s + t^2)^{1/2}}{(\partial_H g)^2 + 4} (-\theta + r \partial_H g t).$$

It follows that

$$\frac{1-h}{1-v} = \frac{\theta \partial_H g + 4rt}{2(-\theta + rt \partial_H g)}.$$

In the vicinity of the boundary $r \to 0$ and, hence,

$$\frac{1-h}{1-v} = -\frac{\partial_H g}{2} = \frac{1-b/a \ e^{-2V_0}}{1-b/a \ e^{-2H_0}} \tag{87}$$

as $h, v \to 1$. Thus, under the Legendre transform, the slope of the line which approaches the corner h = v = 1 depends on the boundary point on the interface between the frozen and disordered regions.

It follows that the first terms of the asymptotics of σ at the corner h=v=1 are given by

$$\sigma(h, v) = -\ln a - 2(1-h)H_0(h, v) - 2(1-v)V_0(h, v),$$

where $H_0(h, v)$ and $V_0(h, v)$ can be found from (87) and $g(H_0, V_0) = 0$.

When $|\Delta| < 1$ the function σ is strictly convex and smooth for all 0 < h, v < 1. It develops conical singularities near the boundary.

When $\Delta < -1$, in addition to the singularities on the boundary, σ has a conical singularity at the point (1/2, 1/2). It corresponds to the "central flat part" of the free energy f, see Fig. 15.

When $\Delta > 1$ the function σ has corner singularities along the boundary as in the other cases. In addition to this, it has a corner singularity along the diagonal v = h if a > b and v = 1 - h if a < b. We refer the reader to [6] for further details on singularities of σ in the case when $\Delta > 1$.

When $\Delta = -1$ function σ has a corner singularity at ((1/2, 1/2).

12 The limit shape phenomenon

12.1 The Height Function for the 6-vertex model

Consider the square grid $L_{\epsilon} \subset \mathbb{R}^2$ with the step ϵ . Let $D \subset \mathbb{R}^2$ be a domain in \mathbb{R}^2 . Denote by D_{ϵ} a domain in the square lattice which corresponds to the intersection $D \cap L_{\epsilon}$, assuming that the intersection is generic, i.e. the boundary of D does not intersect vertices of L_{ϵ} .

Faces of D_{ϵ} which do not intersect the boundary ∂D of D are called *inner* faces. Faces of D_{ϵ} which intersect the boundary of D are called boundary faces.

A height function h is an integer-valued function on the faces of D_{ϵ} of the grid L_N (including the outer faces) which is

- non-decreasing when going up or to the right,
- if f_1 and f_2 are neighboring faces then $h(f_1) h(f_2) = -1, 0, 1$.

Boundary value of the height function is its restriction to the outer faces. Given a function $h^{(0)}$ on the set of boundary faces denote $\mathcal{H}(h^{(0)})$ the space of all height functions with the boundary value $h^{(0)}$. Choose a marked face f_0 at the boundary. A height function is normalized at this face if $h(f_0) = 0$.

Proposition 2. There is a bijection between the states of the 6-vertex model with fixed boundary conditions, and height functions with corresponding boundary values normalized at f_0 .

0]	2	3	4	5
0	1	2	3	4	4
0	1	2	2	3	3
0	0	1	1	2	2
0	0	1	1	1	1
0	0	Ω	Ω	Ω	Ω

Figure 19: The values of the height function for the configuration of paths given on Fig. 5.

Proof. Indeed, given a height function consider its "level curves," i.e. paths on D_{ϵ} , where the height function changes its value by 1, see Fig. 19. Clearly this defines a state for the 6-vertex model on D_{ϵ} with the boundary conditions determined by the boundary values of the height function.

On the other hand, given a state in the 6-vertex model, consider the corresponding configuration of paths. That there is a unique height function whose level curves are these paths and which satisfies the condition h = 0 at f_0 .

It is clear that this correspondence is a bijection. \Box

There is a natural partial order on the set of height functions with given boundary values. One function is bigger than the other, $h_1 \leq h_2$, if it is entirely above the other, i.e. if $h_1(x) \leq h_2(x)$ for all x in the domain. There exist the minimum h_{\min} and the maximum h_{\max} height functions such that $h_{\min} \leq h \leq h_{\max}$ for all height functions h. for DW boundary conditions maximal and minimal height functions ar shown on Fig. 20.

The characteristic function of an edge is related to the hight function as

$$\sigma_e = h(f_e^+) - h(f_e^-) \tag{88}$$

where faces f_e^{\pm} are adjacent to e, f_e^{+} is to the right of e for the vertical edge and on the top for the horizontal one. The face f_e^{-} is on the left for the vertical edge and below e for the horizontal edge.

Thus, we can consider the 6-vertex model on a domain as a theory of fluctuating discrete surfaces constrained between h_{\min} and h_{\max} . Each surface occurs with probability given by the Boltzmann weights of the 6-vertex model.

The height function does not exist when the region i snot simply-connected or when a square lattice is on a surface with non-trivial fundamental group. One can draw analogy between states of the 6-vertex model and 1-forms. States on a domain with trivial fundamental group can be regarded as exact forms $\omega = dh$ where h is a height function.

12.2 Stabilizing Fixed Boundary Conditions

Recall that the height function is a monotonic integer-valued function on the faces of the grid, which satisfies the Lipschitz condition (it changes at most by 1 on any two adjacent faces).

The normalized height function is a piecewise constant function on D_ϵ with the value

$$h^{\text{norm}}(x,y) = \epsilon h_{\epsilon}(n,m).$$

where $h_{\epsilon}(n,m)$ is a height function on D_{ϵ} .

Normalized height functions on the boundary of D satisfy the inequality

$$|h(x,y) - h(x',y')| \le |x - x'| + |y - y'|.$$

As for non-normalized height functions there is a natural partial ordering on the set of all normalized height functions with given boundary values: $h_1 \ge h_2$ if $h_1(x) \ge h_2(x)$ for all $x \in D$. We define the operations

$$h_1 \lor h_2 = \min_{x \in D} (h_1(x), h_2(x)), \qquad h_1 \land h_2 = \max_{x \in D} (h_1(x), h_2(x)).$$

It is clear that

$$h_1 \lor h_2 \le h_1, h_2 \le h_1 \land h_2$$

It is also clear that in this partial ordering there is a unique minimal and maximal height functions, which we denote by h^{min} and h^{max} , respectively.

The boundary value of the height function defines a piecewise constant function on boundary faces of D_{ϵ} . Consider a sequence of domains D_{ϵ} with $\epsilon \to 0$. Stabilizing fixed boundary conditions for height functions is a sequence $\{h^{(\epsilon)}\}$ of functions on boundary faces of D_{ϵ} such that $h^{(\epsilon)} \to h^{(0)}$ where $h^{(0)}$ is a continuous function of ∂D .

It is clear that in the limit $\epsilon \to 0$ we have at least two characteristic scales. At the *macroscopical* scale we can "see" the region $D \subset \mathbb{R}^2$. Normalized height functions in the limit $\epsilon \to 0$ will be functions on D. As we will see in the next

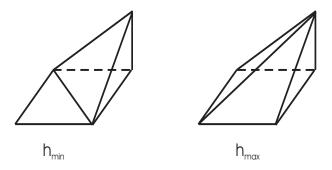


Figure 20: The minimum and maximum height functions for the DW boundary conditions.

section, the height function in the 6-vertex model develops deterministic limit shape $h_0(x,y)$ at this scale. It is reflected in the structure of local correlation functions. Let e_i be edges with coordinates $(n_i, m_i) = (\frac{x_i}{\epsilon}, \frac{y_i}{\epsilon})$. When $\epsilon \to 0$ and (x_i, y_i) are fixed

$$\langle \sigma_{e_1} \dots \sigma_{e_k} \rangle = \partial_{i_1} h_0(x_1, y_1) \dots \partial_{i_k} h_0(x_k, y_k) + O(e^{-\frac{c}{\epsilon}})$$

The randomness remain at the smaller scale, and in particular at the lattice, microscopical, scale. If coordinates of edges e_i are $(n_i, m_i) = (\frac{x}{\epsilon} + \Delta n_i, \frac{y}{\epsilon} + \Delta m_i)$ we expect that in the limit $\epsilon \to 0$ correlation functions have the limit

$$<\sigma_{e_1}\ldots\sigma_{e_k}> \to \sigma_{e_1}\ldots\sigma_{e_k}>_{(\partial_x h_0(x,y),\partial_y h_0(x,y))}$$

where the correlation function at the right side is taken with respect to the translation invariant Gibbs nmeasure with the average polarization $(\partial_x h_0(x,y), \partial_y h_0(x,y))$. The correlator in the r.h.s. depends on the polarization and on $\Delta n_i - \Delta n_j$, $\Delta m_i - \Delta m_j$, i.e. it is translation invariant.

12.3 The Variational Principle

12.3.1

Here we will outline the derivation of the variational problem which determines the limit shape of the height function.

First, consider the sequence of rectangular domain of size M, M when $N, M \to \infty$ such that a = N/M is finite and the boundary values of the height function stabilize to the function $\phi(x,y) = hy + vx, x \in [0,a], y \in [0,1]$. The partition function of such system has the asymptotic

$$Z_{N,M} \propto \exp(NM\sigma(h,v))$$
 (89)

where $\sigma(h, v)$ is the Legendre transform of the free energy for the torus.

For a domain D_{ϵ} , choose a subdivision of it into a collection of small rectangles. Taking into account (89), the partition function of the 6-vertex model with zero electric fields and stabilizing boundary conditions can be written as

$$Z_{D_{\epsilon}} \simeq \sum_{h} e^{|D_{\epsilon}| \sum_{i} \sigma(\Delta h_{x_{i}}, \Delta h_{y_{i}}) \Delta_{x_{i}} \Delta_{y_{i}}}$$

When $\epsilon \to 0$ the size of $|D_{\epsilon}|$ the region is increasing and the he leading contribution to the sum comes from the height function which minimizes the functional

$$I(h) = \int_{D} \sigma(\nabla h) d^{2}x$$

One can introduce the extra weight $q^{vol(h)}$ to the partition function of the 6-vertex model. It corresponds to inhomogeneous electric fields [29]. If $\epsilon \to 0$ and $q = \exp(-\lambda \epsilon)$ the leading contribution to the partition function comes from the height function which minimizes the functional

$$I_{\lambda}(h) = \int_{D} \sigma(\nabla h(x)) d^{2}x + \lambda \int_{D} h(x) d^{2}x$$

12.3.2 The variational principle

Thus, in order to find the limit shape in the thermodynamical limit of the 6-vertex model on a disc with Dirichlet boundary conditions φ_0 , we should minimize the functional

$$I_{\lambda}[\varphi] = \int_{D} \sigma(\nabla \varphi) d^{2}x + \lambda \int_{D} \varphi d^{2}x, \tag{90}$$

on the space $L(D, \varphi_0)$ of functions satisfying the Lipshitz condition

$$|\varphi(x,y) - \varphi(x',y')| \le |x - x'| + |y - y'|$$

and the boundary conditions monotonically increasing in x and y directions

$$\varphi|_{\partial D} = \varphi_0.$$

Since σ is convex, the minimizer is unique when it exists. Thus, we should expect that the variational problem (90) has a unique solution.

The large deviation principle applied to this situation should result in the convergence in probability, as $\epsilon \to 0$ of random normalized height functions h(x, y) to the minimizer of (90).

12.3.3

If the vector $\nabla h(x, y)$ is not a singular point of σ , the minimizer h satisfies the Euler-Lagrange equation in a neighborhood of (x, y)

$$\operatorname{div}(\nabla \sigma \circ \nabla h) = \lambda. \tag{91}$$

We can also rewrite this equation in the form

$$\nabla \sigma(\nabla h(x,y)) = \frac{\lambda}{2} (x,y) + (-g_y(x,y), g_x(x,y)), \tag{92}$$

where g is an unknown function such that $g_{xy}(x,y) = g_{yx}(x,y)$. It is determined by the boundary conditions for h.

Applying (85), it follows that

$$\nabla h(x,y) = \nabla f\left(\frac{\lambda}{2}x - g_y(x,y), \frac{\lambda}{2}y + g_x(x,y)\right). \tag{93}$$

From the definition of the slope, see (54), it follows that $|f_H| \leq 1$ and $|f_V| \leq 1$. Thus, if the minimizer h is differentiable at (x,y), it satisfies the constrains $|h_x| \leq 1$ and $|h_y| \leq 1$. It is given that $h_x, h_y \geq 0$, hence, $0 \leq h_x \leq 1$ and $0 \leq h_y \leq 1$.

In particular, one can choose g(x,y)=0. In this case the function (93) is the minimizer of the rate functional $I_{\lambda}[h]$ with very special boundary conditions. For infinite region D (and finite λ) this height function reproduces the free energy as a function of electric fields.

The limit shape height function is a real analytic function almost everywhere. One of the corollaries of (93) is that curves on which it is not analytic (interfaces of the limit shape) are images of boundaries between different phases in the phase diagram of f(H, V). The ferroelectric and antiferroelectric regions, where f is linear, correspond to the regions where h is linear.

From (93) and the asymptotic of free energy near boundaries between different phases, we can make some general conclusions about the the structure of limit shapes.

First conclusion is that near regular pieces of boundary between regions where the height function is real analytic it behaves as $h(x, y) - h(x_0, y_0) \simeq d^{3/2}$ where d is the distance from (x, y) to the closest point (x_0, y_0) at the boundary.

Second obvious conclusion is that if (x,y) is inside the corner singularity in the boundary between smooth parts, the height function behaves near the corner as $h(x,y) - h_(x_0,y_0) \simeq d^{5/3}$ where d is the distance from (x,y) to the corner, and (x_0,y_0) are coordinates of the corner.

12.4 Limit shapes for inhomogeneous models

So far the analysis of limit shapes was done in the homogeneous 6-vertex model. The variational problem determining limit shapes involves the free energy as the function of the polarization. The extension of the analysis outlined above to an inhomogeneous periodically weighted case is straightforward. The variational principle is the same same but the function σ is determined from the Bethe ansatz for the inhomogeneous model. It is again the Legendre transform of the free energy as a function of electric fields.

The computation of the free energy from the large N asymptotic of Bethe ansatz equations is similar and based on similar conjecture about the accumulation of solutions to Bethe equations on a curve. In the free fermionic case it is illustrated in section 8. If the size of the fundamental domain is $k \times m$ one should expect 2(k+m) cusps in the boundary between ordered and disordered regions.

12.5 Higher spin 6-vertex model

The weights in the 6-vertex model can be identified with matrix elements of the R-matrix of $U_q(\hat{sl}_2)$ in the tensor product of two 2-dimensional representations of this algebra. We denoted such matrix $R^{(1,1)}(z)$.

In a similar fashion one can consider matrix elements of $R^{(l_1,l_2)}(z)$ as weights of the higher spin generalization of the 6-vertex model. We will call it higher spin 6-vertex model.

A state in such models is an assignment of a weight of the irreducible representation $V^{(l_1)}$ to every horizontal edge, and of a weight of the irreducible representation of $V^{(l_2)}$ to every vertical edge.

Natural local observables in such model are sums of products of spin func-

tions of an edge:

 $s_e(S)$ = the weight s assigned to e in the state S,

Spin variables define the height function locally as

$$s_e = h(f_e^+) - h(f_e^-)$$

where f_e^{\pm} are faces adjacent to e. When the domain has trivial fundamental group the local height function extends to a global one. Otherwise one should the region into simply-connected pieces.

The height function has the property

$$|h(n,m) - h(n',m')| \le l_1|n-n'| + l_2|m-m'|,$$

Given a sequence of domains D_{ϵ} with $\epsilon \to 0$ one should expect that the normalized height function $\epsilon h(\epsilon n, \epsilon m)$ develops the limit shape $h_0(x, y)$ which minimizes the functional

$$I^{(l_1,l_2)}[h] = \int_D \sigma^{(l_1,l_2)}(\nabla h) d^2x$$

subset to the Dirichlet boundary conditions and the constraint

$$|h(x,y) - h(x',y')| \le l_1|x - x'| + l_2|y - y'|,$$

The properties of such model and of its free energy as function of electric fields is an interesting problem which need further research.

13 Semiclassical limits

13.1 The semiclassical limits in Bethe states

The spectrum of quantum spin chains described in section 4 in terms of Bethe equations has a natural limit when $m_i = R_i/h$, $q = e^h$, and $h \to 0$ with fixed R_i . In this limit the quantum spin chain with the quantum monodromy matrix (35) becomes the classical spin chain with the monodromy matrix (11).

Semiclassical eigenvectors of quantum transfer-matrices correspond to solutions to Bethe equations which accumulate along contours representing branch cuts on the spectral curve of T(z), see [31] and for more recent results [36].

13.2 The semiclassical limits in the higher spin 6-vertex model

Relatively little known about the semiclassical limit of the higher spin 6-vertex model. This is the limit when $l_1 = R_i/h$, and $h \to 0$. Here, depending on the values of Δ , $h = \eta$ or $h = \gamma$.

The first problem is to find the asymptotic of the conjugation action of the R-matrix in this limit. The mapping

$$x \to R^{(l_1, l_2)}(u) x R^{(l_1, l_2)}(u)^{-1}$$

is an automorphism of $End(V^{(l_1)} \otimes V^{(l_2)})$ which as $h \to 0$ becomes the Poisson automorphism $\rho^{(R_1,R_2)}(u)$ of the Poisson algebra of functions on $S^{(R_1)} \otimes S^{(R_2)}$.

When $\Delta = 1$ this automorphism was computed in [35]. It is easy to extend this results for $\Delta \neq 1$. For constant R-matrices see [30].

Next problem is to find the semiclassical asymptotic for the R-matrix considered as an "evolution operators". For this one should choose two Lagrangian submanifolds in $S^{(R_1)} \otimes S^{(R_2)}$, one corresponding to the initial data and the other corresponding to the target data. Points in these manifolds parameterize corresponding semiclassical states. Then matrix elements of the R-matrix should have the asymptotic

$$R^{(l_1,l_2)}(u)(\sigma_1,\sigma_2) = const \exp \frac{S^{(R_1,R_2)}(\sigma_1,\sigma_2)}{h} \sqrt{H(\sigma_1,\sigma_2)}(1+O(h))$$

where S is the generating function for the mapping ρ and H is the Hessian of S. This asymptotical behavior of the R-matrix defines the semiclassical limit of the partition function and needs further investigation.

13.3 The large N limit in spin-1/2 spin chain as a semiclassical limit

13.3.1

Local spin operators in a spin-1/2 spin chain of length N are

$$S_n^a = 1 \otimes \dots \sigma_n^a \otimes \dots \otimes 1, \quad n = 1, \dots, N$$

They commute as

$$[S_n^a, S_m^b] = i \sum_c \epsilon_{abc} \delta_{nm} S_n^c$$

As $N \to \infty$ the operators S_n^a converge to local continuous classical spin variables

$$S_n^a \to S^a(\frac{n}{N})$$

where $S^a(x)$ are local functionals on the classical phase space of the continuum spin system. The commutation relations become the relations between Poisson brackets:

$$\{S^{a}(x), S^{b}(y)\} = \delta(x - y) \sum_{c} f_{c}^{ab} S^{c}(x)$$

where $S^a(x)$ are continuous local classical spin variables. This combination of classical and continuous limit looks more convincing in terms of observables

$$S_N^a[f] = \frac{1}{N} \sum_{n=1}^N f(\frac{n}{N}) S_n^a,$$

As $N \to \infty$, such operators becomes $S^a[f] = \int_0^1 f(x) S^a(x) dx$ and the commutation relation

$$[S_N^a[f], S_N^b[g]] = \frac{i}{N} \sum_c \epsilon_{abc} S_N^c[fg]$$

becomes

$$\{S^a[f], S^b[g]\} = \sum_{c} \epsilon_{abc} S^c[fg]$$

Here we used the asymptotic of commutators in the semiclassical limit: $[a, b] = ih\{a, b\} + \dots$ and the fact that $\frac{1}{N}$ plays the role of the Plank constant.

13.3.2

Consider the limit $N \to \infty$ of the row-to-row transfer-matrix in the 6-vertex model. Assume that at the same time $\Delta \to 1$ such that $\Delta = 1 + \frac{\kappa^2}{2N^2} + \dots$ To be specific consider the case when $\Delta > 1$, so that $\kappa = N\eta$ is finite and real.

We can write the transfer-matrix of the 6-vertex model as

$$t(u) = (\sinh(u))^N tr(T_N(u)),$$

where $T_N(u)$ is the solution to the difference equation

$$T_{n+1}(u) = \frac{R_n(u)}{\sinh(u)} T_n(u)$$

with the initial condition $T_0(u) = 1$. Here R(u) is the R-matrix of the 6-vertx model. For small η we have:

$$\frac{R_n(u)}{\sinh(u)} = 1 + \eta(\frac{1}{2}\coth(u)\sigma^3\sigma_n^3 + \frac{\sigma^+\sigma_n^- + \sigma^-\sigma_n^+}{\sinh(u)}) + O(\eta^2)$$

Taking this into account we conclude that as $N \to \infty$, $T_n(u) \to T(u|x)$ where T(u|x) is the solution to

$$\frac{\partial T(u|x)}{\partial x} = (\frac{1}{2}\coth(u)\sigma^3 S^3(x) + \frac{\sigma^+ S^-(x) + \sigma^- S^+(x)}{\sinh(u)})T(u|x)$$

with the initial condition T(u|0)=1. Here σ^z is the same as in (32), $\sigma^{\pm}=\frac{1}{2}(\sigma^x\pm i\sigma^y)$, and $S^{\pm}=\frac{1}{2}(S^1\pm iS^2)$

The row-to-row transfer-matrix of the 6-vertex model have the following asymptotic in this limit:

$$t(u) \to (\sinh(u))^N \tau(u)$$
 (94)

where $\tau(u) = tr(T(u|1).$

13.3.3

Now let us study the evolution of local spin operators in this limit.

Consider the partition function of the 6-vertex model on a cylinder as a liner operator $\,$

$$Z_{M,N}^{(C)} = t(u)^M$$

acting in $\mathbb{C}^{2^{\otimes N}}$. Consider the row-to-row transfer-matrix as the evolution operator by one step and $Z_{M,N}^{(C)}$ as the evolution operator by M steps. In the Heisenberg picture, local spin operators evolve as:

$$S_{n,m+1}^a = t(u)S_{n,m}^a t(u)^{-1} (95)$$

In the continuum semiclassical limit $N \to \infty$ the transfer-matrix becomes a functional (94) on the phase space of continuous classical spins. The equation (95) can be written as

$$S_{n,m+1}^a - S_{n,m}^a = [t(u), S_{n,m}^a]t(u)^{-1}$$

As $N \to \infty$ and x = n/N and t = m/N are fixed, this equation become the evolution equation for continuum spins:

$$\frac{\partial S^a(x,t)}{\partial t} = \{H(u), S^a(x,t)\}$$

where $H(u) = \log t(u)$.

The evolution with respect to the partition function on a cylinder of height ${\cal M}$

$$S_{n,m+M}^a = Z_{M,N}^{(C)} S_{n,m}^a Z_{M,N}^{(C)}^{-1}$$

becomes the evolution in time T = M/N: $S^a(x,t) \mapsto S^a(x,t+T)$.

If we choose a Lagrangian submanifold in the phase space of continuous spin system corresponding to the initial and target data (say, a version of initial and target q-coordinates), the asymptotic of the partition function should be of the form

$$Z_{NM}^{(C)}(\sigma_1, \sigma_2) = conste^{-NS_T(\sigma_1, \sigma_2)} \sqrt{Hess(\sigma_1, \sigma_2)} (1 + O(1/N))$$

where S_T is the Hamilton-Jacobi action for the Hamiltonian H(u), $Hess(\sigma, \tau)$ is the Hessian of S_T , and in the left side we have the matrix element of $Z_{N,M}^{(C)}$ between semiclassical states corresponding to σ_1 and to σ_2 .

The Bethe equations and the spectrum of the Heisenberg Hamiltonian in this limit was studied in [12][9].

14 The free fermionic point and dimer models

Decorate the square grid inserting a box with two faces to each vertex, as it is shown on Fig. 22. Recall that a dimer configuration on a graph is a perfect

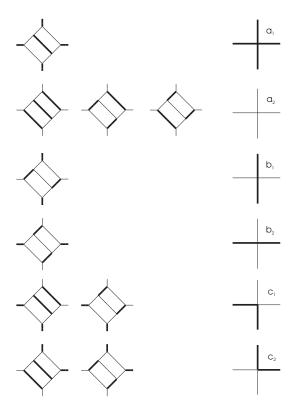


Figure 21: Projection of dimer configurations on $G_{nm}^{(0)}$ onto the different types of vertices at the (n, m)-vertex.

matching on a set of vertices connected by edges. In other words, it is a collection of "occupied edges" (by dimers) such that two occupied edges never meet, and any vertex in an endpoint to an occupied edge.

Dimer configurations on the decorated square grid project to 6-vertex configurations on a square grid as it is shown on Fig. 21.

It is easy to check that any edge weight system on the decorated lattice projects to 6-vertex weights at the free fermionic point, when $a^2 + b^2 - c^2 = 0$ at every vertex. Recall that edge weights is a mapping $w : \text{Edges} \to \mathbb{R}_{\geq 0}$. The weight of a dimer configuration is

$$W(D) = \prod_{e \in D} w(e)$$

The statement above means

$$\sum_{D \in \pi^{-1}(S)} W(D) = \prod_v w_v(S)$$

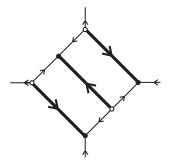


Figure 22: Reference dimer configuration on $G_{nm}^{(0)}$.

where S is a 6-vertex configuration on the square grid, π is the projection from dimer configurations on the decorated square grid to the 6-vertex configurations, and the 6-vertex weights w_v are given by an explicit formula. The weights w_v satisfy the free fermionic condition.

A pair of dimer configurations D, D_0 on bipartite graphs define the height function. This height function agrees with the height function of the 6-vertex model:

$$h_S(f) = h_{D,D_0}(f)$$

where S is a 6-vertex state on the square lattice, and h_S is the corresponding height function, $D \in \pi^{-1}(S)$, D_0 is shown on Fig. 22, and f is the face of the decorated lattice which projects to a face of the square grid.

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A Symplectic and Poisson manifolds

A.1

Recall that an even dimensional manifold equipped with a closed non-degenerate 2-form is called *symplectic*.

Let (\mathcal{M}, ω) be a 2n-dimensional symplectic manifold. In local coordinates:

$$\omega = \sum_{ij=1}^{2n} \omega_{ij} dx^i \wedge dx^j, \quad \det(\omega) \neq 0, \quad d\omega = \sum_{k=1}^{2n} \sum_{ij=1}^{2n} \frac{\partial \omega_{ij}}{\partial x^k} dx^i \wedge dx^j = 0,$$

The last identity is equivalent to the Jacobi identity for the bracket

$$\{f,g\} = \sum_{ij=1}^{2n} (\omega^{-1})^{ij} \frac{\partial f}{x^i} \frac{\partial g}{x^j}$$

A.2

A smooth manifold M with bi-vector field p (a section of the bundle $\wedge^2 TM$) such that the bracket between two smooth functions

$$\{f,g\} = p(df \wedge dg)$$

satisfies the Jacobi identity is called a Poisson manifold. I local coordinates $x^1, \ldots, x^n, p(x) = \sum_i i, j = 1^n p^{ij}(x) \frac{\partial}{\partial x^i} \wedge \frac{\partial}{\partial x^i}$.

A.3

A Poisson tensor on a smooth manifold M defines a subspace mapping $p: T^*M \to TM$. The image is a system of subspaces $p(T^*M) \subset TM$ which is a distribution on M. Leaves of this distribution are spanned by curves which are flow lines of piece-wise Hamiltonian vector fields. They are smooth submanifolds. Symplectic leaves of the Poisson manifold M are leaves of this distribution.

Well know examples of symplectic leaves are co-adjoint orbits in the dual space to a Lie algebra.

B Classical integrable systems and their quantization

B.1 Integrable systems in Hamiltonian mechanics

The notion of integrability is most natural in the Hamiltonian formulation of classical mechanics. For details see [2] [33].

In Hamiltonian formalism of classical mechanics the dynamics is taking place on the phase space and equations of motion are of the first order. When it is a system of particles moving on a manifold M, local coordinates are positions and momenta of particles. Globally, the phase space in this case is the cotangent bundle to the manifold M, see for example [2].

Hamiltonian formulation of spinning tops or other systems with more complicated constraints involves more complicated phase spaces. In all cases a phase space has a structure of a structure of a symplectic manifold, that is it comes together with a non-degenerate closed 2-form on it.

Any symplectic manifold (and so any phase space of a Hamiltonian system admits local coordinates (Darboux coordinates) in which the 2-form has the form

$$\omega = \sum_{i=1}^{n} dp_i \wedge dq^i$$

These coordinates can be interpreted as momenta and positions, though in case of spinning tops this interpretation does not have a lot of physical meaning but Darboux coordinates is a convenient mathematical tool.

The dynamics in a Hamiltonian system is determined by the energy function H. The trajectories of such system in local Darboux coordinates are solutions to differential equations:

$$\frac{dq^{i}}{dt} = \frac{\partial H}{\partial p_{i}}, \quad \frac{dp_{i}}{dt} = -\frac{\partial H}{\partial q^{i}}$$

Geometrically, trajectories are flow lines of the Hamiltonian vector field $v_H = \omega^{-1}(dH) \in \Gamma(\wedge^2 TM)$ where $\omega^{-1}: TM \to T^*M$ is the bundle isomorphism induced by the symplectic form ω .

Let \mathcal{M} be a 2N-dimensional symplectic manifold.

Definition 1. An integrable system on M is a collection of N independent functions on M which commute with respect to the Poisson bracket.

Recall that

• The "level surfaces"

$$\mathcal{M}(c_1, \dots, c_n) = \{ x \in \mathcal{M}, I_i(x) = c_i \}$$

$$(96)$$

are invariant with respect to the flow of any Hamiltonian $H = F(I_1, \ldots, I_N)$.

- For every such Hamiltonian and every level surface $\mathcal{M}(c_1,\ldots,c_n)$ there exists an affine coordinate system (p_1,\ldots,p_n) in which the Hamiltonian flow generated by H is linear: p_i =constant.
- The coordinate system (p_1, \ldots, p_n) on $\mathcal{M}(c_1, \ldots, c_n)$ can be completed to a canonical coordinate system (p_i, q_j) in every sufficiently small neighborhood of $\mathcal{M}(c_1, \ldots, c_n)$. These coordinates are called action-angle variables and in some cases these coordinates are global.

C Poisson Lie groups

C.1 Poisson Lie groups

A Lie group G is called a Poisson Lie group if

• G has a Poisson structure, i. e. it is given together with the Poisson tensor $p \in \Gamma(\wedge^2 TG)$, in local coordinates $p(x) = p^{ij}(x) \frac{\partial}{\partial x^i} \wedge \frac{\partial}{\partial x^j} \in \wedge^2 T_x G$. This tensor the Poisson bracket on smooth functions on G (Lie bracket satisfying the Leibnitz rule with respect to the point-wise multiplication)

$$\{f,g\}(x) = \sum_{ij} p^{ij}(x) \frac{\partial f}{\partial x^i} \frac{\partial g}{\partial x^j}(x)$$

• The Poisson structure is compatible with the group multiplication. This means that the multiplication mapping $G \times G \to G$ bring the Poisson tensor on $G \times G$ to the Poisson tensor on G, or:

$$\sum_{ij} p^{ij}(xy) \frac{\partial f}{\partial z^i} \frac{\partial g}{\partial z^j}(z)|_{z=xy} = \sum_{ij} p^{ij}(x) \frac{\partial f}{\partial x^i} \frac{\partial g}{\partial x^j}(xy) + \sum_{ij} p^{ij}(y) \frac{\partial f}{\partial y^i} \frac{\partial g}{\partial y^j}(xy)$$

for any pair of functions f, g.

For more details on Poisson Lie groups and for numerous examples see [11][8][21].

C.2 Factorizable Poisson Lie groups and classical r-matrices

The class of Poisson Lie groups relevant to integrable systems has so-called r-matrix Poisson brackets. Let $\mathfrak g$ be a Lie algebra corresponding to the Lie group G. A classical r-matrix for G is an element $r \in \mathfrak g \otimes \mathfrak g$ satisfying the bilinear identity

$$[r_{12}, r_{13}] + [r_{12}, r_{23}] + [r_{13}, r_{23}] = 0 (97)$$

The Poisson tensor

$$p(x) = r - Ad_x(r) \in \mathfrak{g} \wedge \mathfrak{g}$$

defines a Poisson Lie structure on G if r satisfies (97) and $r + \sigma(r)$ is an invariant tensor.

Two remarks: we identified $T_xGwithT_eG=\mathfrak{g}$ using left translations on G; Ad_x is the diagonal adjoint action of G on $\mathfrak{g} \wedge \mathfrak{g}$, $u \wedge v \to xux^{-1} \otimes xvx^{-1}$ when G is a matrix Lie algebra.

Let $\pi^V: G \to GL(V)$ and $\pi^W: G \to GL(W)$ be two (finite-dimensional) representations of G and let π^V_{ij}, π^W_{ab} be matrix elements of G in a linear basis: $\pi^V_{ij}: g \in G \to \pi^V_{ij}(g) \in \mathbb{C}$. The r-matrix Poisson brackets between two such functions are:

$$\{\pi_1^V, \pi_2^W\} = [(\pi^V \otimes \pi^W)(r), \pi_1^V, \pi_2^W]$$

Taking trace in this formula we see that characters of finite dimensional representations form a Poisson commutative algebra on G. Restricting this subalgebra to a symplectic leaf of G we will obtain an integrable system if the number of independent functions among χ_{λ} after this restriction is equal to half of the dimension of the symplectic leaf.

the principal advantage of this approach is that it gives an algebraic way to construct classical r-matrices through the double construction of Lie bi-algebras.

In then next section we will see how r-matrices with spectral parameter appear naturally from Lie bi-algebras on loop algebras.

C.3 Basic example $G = LSL_2$

Our basic example is an infinite dimensional Poisson Lie group LGL_2 of mappings $S^1 = \{z \in \mathbb{C} | |z| = 1\} \to GL_2$ which are holomorphic inside the unit disc.

The Lie algebra Lgl_2 (we consider maps which are Laurent polynomials in t) of the Lie group LGL_2 has a linear basis $e_{ij}[n]$ with $e_{ij}[n](z) = e_{ij}t^{-n-1}$. It also has an invariant scalar product $(x[n], y[m]) = \delta_{n,m}$. The following element of the completed tensor product $Lgl_2 \otimes Lgl_2$

$$r = \sum_{i \ge j; i, i=1,2} e_{ij}[0] \otimes e_{ji}[0] + \sum_{i,j=1,2; n \in \mathbb{Z}, n \ge 1} e_{ij}[n] \otimes e_{ji}[-n]$$
 (98)

satisfies the classical Yang-Baxter equation (97). We will not explain here why, but this follows from the Drinfeld's double construction for Lie bialgebras.

Let $\pi^V: GL_2 \to GL(V)$ be a representation of GL_2 and $a \in \mathbb{C}^{\vee}$ be a non-zero complex number. The evaluation representation $\pi_{V,a}$ of Lgl_2 acts in V

$$\pi_{V,a^2}(x[n]) = \pi^V(x)a^{-2n-2}$$

where a is a non-zero complex number.

Evaluating the element (98) in $\pi_{V,a} \otimes \pi_{V,b}$ where V is the two dimensional representation we get

$$\pi_{V,a} \otimes \pi_{V,b}(r) = r(a/b) + f(a/b)1$$

where f(z) is a scalar function and

$$r(z) = \frac{z + z^{-1}}{z - z^{-1}} \sigma^z \otimes \sigma^z + \frac{2}{z - z^{-1}} (\sigma^+ \otimes \sigma^- + \sigma^- \otimes \sigma^+)$$
 (99)

Here $\sigma^z = e_{11} - e_{22}$, $\sigma^+ = e_{12}$, and $\sigma^- = e_{21}$ are Pauli matrices. The Yang-Baxter equation for r implies

$$[r_{12}(z), r_{13}(zw)] + [r_{12}(z), r_{23}(w)] + [r_{13}(zw), r_{23}(w)] = 0$$

The Poisson bracket between coordinate functions $g_{ij}(z)$ are

$$\{g_1(z), g_2(w)\} = [r(z/w), g_1(z)g_2(w)] \tag{100}$$

One of the important properties of such Poisson brackets is that characters of finite dimensional representations define families of Poisson commuting functions on LG_2 :

$$t_V(z) = tr_V(\pi^V(g(x)), \{t_V(z), t_W(w)\} = 0$$

The coefficients of these functions will produce Poison commuting integrals of motions for integrable systems, when restricted to symplectic leaves of LGL_2 .

C.4 Symplectic leaves

It is a well know, classical fact, which can be traced back to works of Lie, that symplectic leaves of the Poisson manifold which is the dual space to a Lie algebra are co-adjoint orbits. Similarly, symplectic leaves of a Poisson Lie group G are orbits of the dressing action of the dual Poison Lie group on G.

The structure of symplectic leaves of Poisson Lie groups is well known for finite dimensional simple Lie algebras, see [21][38]. For the construction of integrable spin chains related to SL_2 we will need only some special symplectic leaves of LGL_2 . These symplectic leaves are symplectic leaves of finite dimensional Poisson submanifolds of polynomial maps of given degree.

D Quantization

D.1 Quantization

This section is a brief outline of the quantization of Hamiltonian systems. There is also a very important point of view of a path integral quantization. We will not discuss it here.

D.1.1 Quantized algebra of observables

Let M be a symplectic manifold, which is the phase space of our mechanical system. We want to describe possible quantum mechanical systems which reproduce our system in the classical limit. This procedure is called quantization.

Let A be a Poisson algebra over \mathbb{C} i.e. it is a complex vector space with a commutative multiplication ab and with the Lie bracket $\{a,b\}$ such that $\{a,bc\}=b\{a,c\}+\{a,b\}c$. Let $X\subset\mathbb{C}$ is a neighborhood of $0\in\mathbb{C}$.

Definition 2. A deformation quantization of A is a family of associative algebras A_h , parameterized by $h \in X$ together with two families of linear maps $\phi_h : A_h \to A$ and $\psi_h : A \to A_h$ such that

- $\lim_{h\to 0} \phi_h \circ \psi_h \to id_A$,
- $\lim_{h\to 0} \phi_h(\psi_h(a)\psi_h(b)) = ab$,
- $\bullet \ \lim_{h \to 0} \frac{\phi_h(\psi_h(a)\psi_h(b) \psi_h(a)\psi_h(b))}{ih} = \{a,b\},\,$

Denote by C(M) the classical algebra of observables, i.e. the algebra of real valued functions on the phase space. If M is T^*N , this will be the algebra of functions on M which are polynomial in the cotangent direction and smooth on N. If M is an affine algebraic, manifold, C(M) will be algebra of polynomial functions. If M is a smooth manifold it is $C^{\infty}M$, etc.. The space C(M) has a natural structure of a Poisson algebra with the point-wise multiplication and the Poisson bracket determined by the symplectic form on M.

Denote its complexification by $C(M)_{\mathbb{C}}$. The real subalgebra $C(M) \subset C(M)_{\mathbb{C}}$ is the set of fixed points of complex conjugation, i.e. real valued functions. Denote complex conjugation by σ , i. e. $\sigma(f)(x) = \overline{f(x)}$.

Deformation quantizations which are relevant to quantum mechanics are real deformation quantizations:

Definition 3. A real deformation quantization of C(M) is a pair $(A_h, \sigma_h, h \in X \subset \mathbb{R})$ where A_h is a deformation quantization (as above) of $C(M)_{\mathbb{C}}$, h is a real deformation parameter, and σ_h is a \mathbb{C} -anti-linear anti-involution of A_h , i.e.

$$\sigma_h^2 = 1$$
, $\sigma_h(ab) = \sigma_h(b)\sigma_h(a)$, $\sigma_h(sa) = \bar{s}\sigma_h(a)$,

The the subspace $C(M)_h \subset A_h$ of fixed points of σ_h is called the space of quantum observables. Linear maps ϕ_h and ψ_h from the definition $f(A_h)$ should satisfy extra condition

$$\lim_{h\to 0}\phi_h\circ\sigma_h\circ\psi_h=\sigma$$

The space of fixed points of σ_h is called the *space of quantum observables*. Notice that the multiplication does not preserve this space. However, it is closed with respect to operations AB+BA and i(AB-BA). Such structures are called Jordan algebras.

Of course these definition still need a clarification. The vector space C(M) is infinite dimensional and we have to specify in which topology our linear isomorphism is continuous and in which sense we should take limits. The way how to handle this is either dictated by the nature of a specific problem, so we will discuss it later in relation to integrable spin chains which is the main subject here.

D.2 Examples of family deformations

D.2.1

Take $M = \mathbb{R}^2$, $A = Pol_{\mathbb{C}}(\mathbb{R}^2) = \mathbb{C}[p,q]$ with the standard symplectic form $dp \wedge dq$ giving the bracket $\{p,q\} = 1$ (this determines the bracket). We have a natural monomial basis p^nq^m on A. Define

$$A_h = \langle p, q | pq - qp = h \rangle$$

It is clear that this is a family of associative algebras. To identify this family with a deformation quantization of A we should find ϕ_h and ψ_h . For this choose monomial bases p^nq^m in A_h and A. Define linear maps ϕ_h and ψ_h as linear isomorphisms $A_h \simeq A$ identifying the monomial bases. It is clear that this choice makes A_h into a defromation quantization of A.

D.2.2

Let \mathfrak{g} be a Lie algebra, and consider $Pol(\mathfrak{g}^*) = \mathbb{C}[\mathfrak{g}]$. If $\{e_i\}$ is a basis for \mathfrak{g} , then we can think of the e_i as coordinate functions x_i on \mathfrak{g}^* . A theorem of Kostant, $\{f,g\}(x) = \langle x, [df(x), dg(x)] \rangle$, $\{x_i, x_j\} = \sum_k c_{ij}^k x_k$. $Pol(\mathfrak{g}^*)$ then gets a Poisson bracket.

We can get a deformation quantization

$$A_h = \langle x_1, \dots, x_n | x_i x_j - x_j x_i = h \sum_k c_{ij}^k x_k \rangle$$

Note that $A_h \cong U\mathfrak{g}$ for any $h \neq 0$ (you just have to rescale the x's by h). On the other hand, Choosing the monomial basis $x_1^{a_1} \cdots x_n^{a_n}$ in $\mathbb{C}[x_1, \ldots, x_n]$ and the PBW basis in A_h . Identifying them, we get $A_h \cong \mathbb{C}[x_1, \ldots, x_n]$, which is how the PBW theorem is usually formulated.

$$U\mathfrak{g}\cong Pol(\mathfrak{g}^*)\cong S(\mathfrak{g})$$

We get a linear isomorphism $\phi_h: A_h \cong A$. It is easy to check that this is a deformation quantization.

D.3 Quantization of integrable systems

As we have seen above the quantization of a classical Hamiltonian system on \mathcal{M} with the Hamiltonian $H \in C(M)$ consists of the following:

- A family of associative algebras A_h quantizing the algebra of function on \mathcal{M} .
- The choice of quantum Hamiltonian $H_h \in A_h$ for each h, such that $\phi_h(H_h) \to H$ as $h \to 0$.

The quantization is integrable if for each h there is a maximal commutative subalgebra of $C_h(M)$ quantizing the subalgebra of classical integrals in C(M), which contains H_h .

To be more precise, let $I(M) \in C(M)$ be the subalgebra generated by Poisson commuting integrals in the classical algebra of observables, i.e. $\{H,F\}=0$ for each $F \in I(M)$ and $\{G,F\}=0$ for each $F,G \in I(M)$. Its integrable quantization consists of a commutative subalgebra $I_h \in A_h$ such that FH=HF for each $F \in I_h$, such that $\lim_{h\to 0} \phi_h(I_h) = I$. For the precise definition in case of formal deformation quantization see [32].

When quantized algebra of observables is represented in a Hilbert space, the important problem is the computation of the spectrum of commuting Hamiltonians.